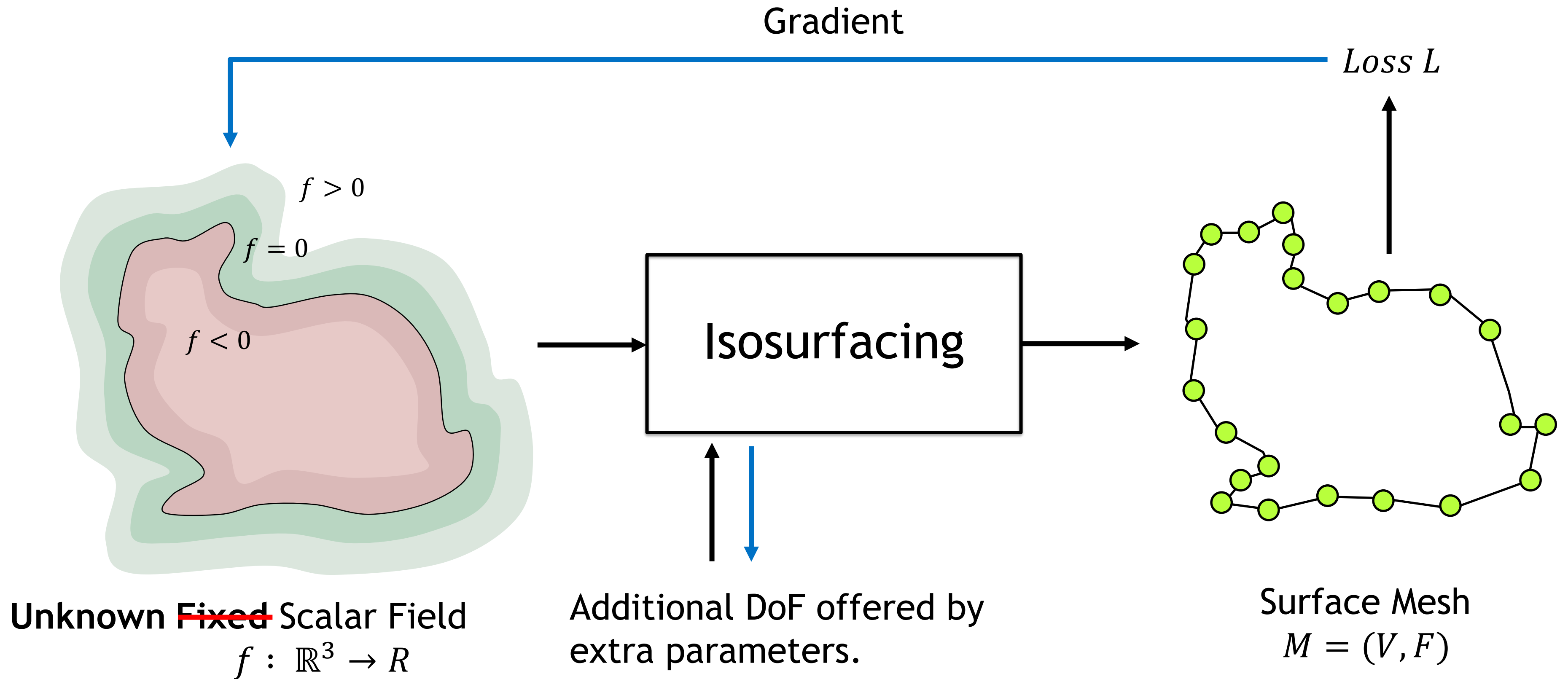




Flexible Isosurface Extraction for Gradient-Based Mesh Optimization

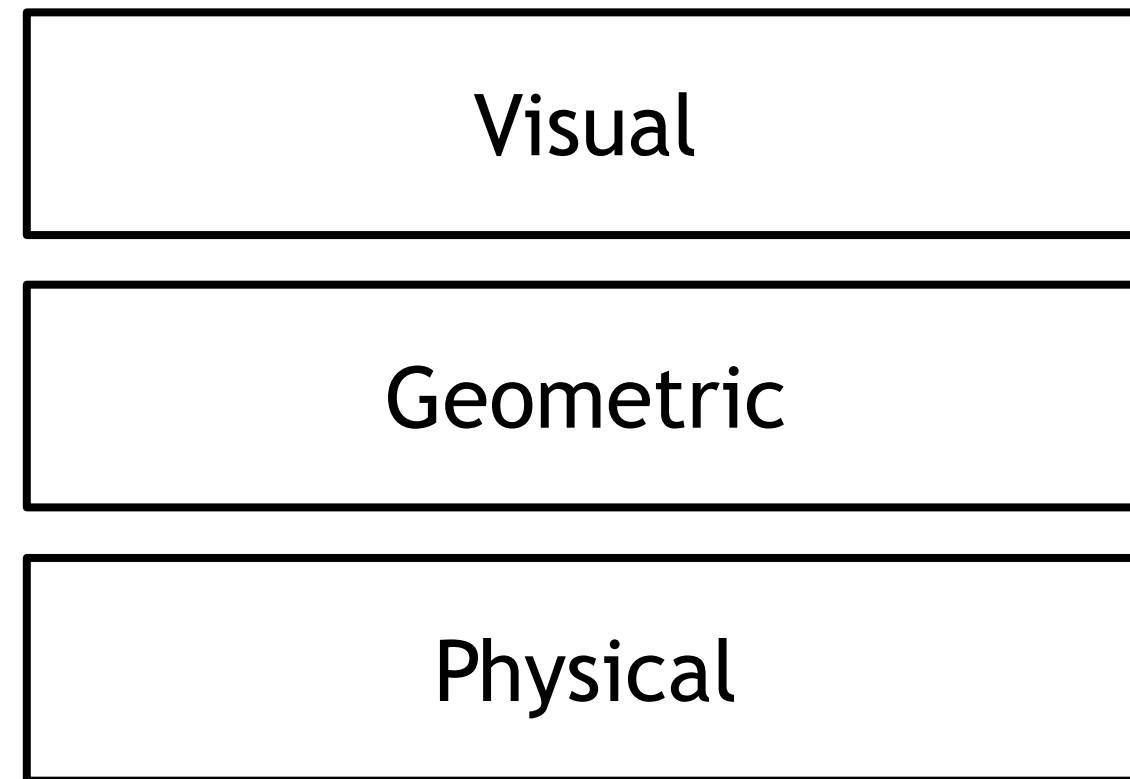
Tianchang Shen, Jacob Munkberg, Jon Hasselgren, Kangxue Yin, Zian Wang,
Wenzheng Chen, Zan Gojcic, Sanja Fidler, Nicholas Sharp*, Jun Gao*

ISOSURFACING



GENERATING MESH VIA GRADIENT-BASED OPTIMIZATION

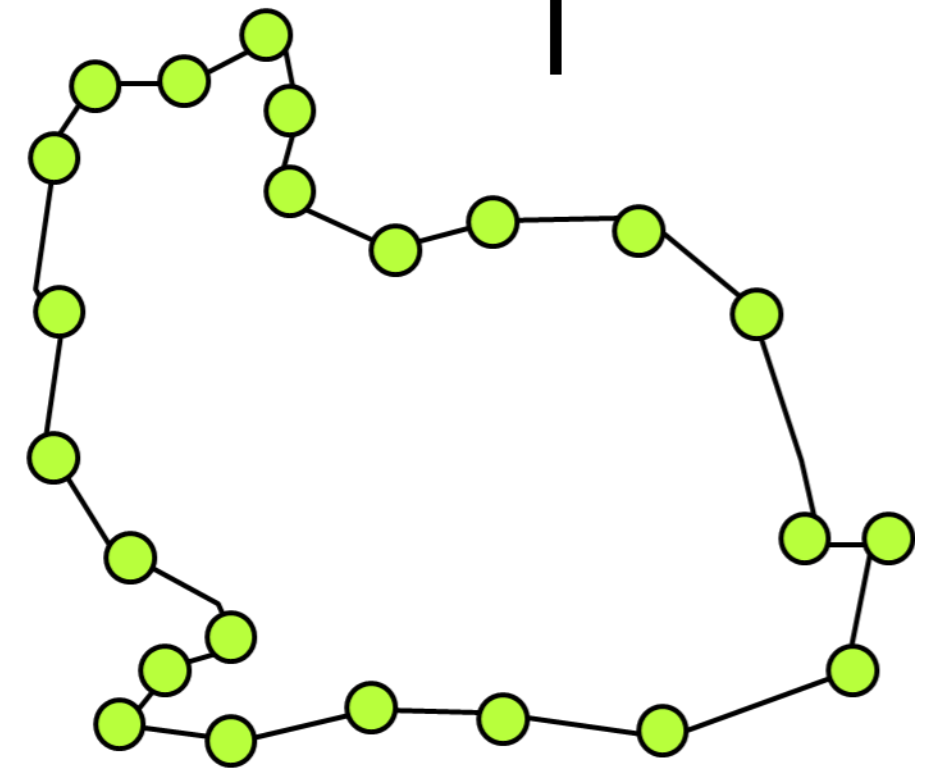
Why not directly optimize the implicit field?



Evaluating objectives on meshes:

- ✓ Efficient, benefit from mesh representation.
- ✓ Ready to use in downstream applications.

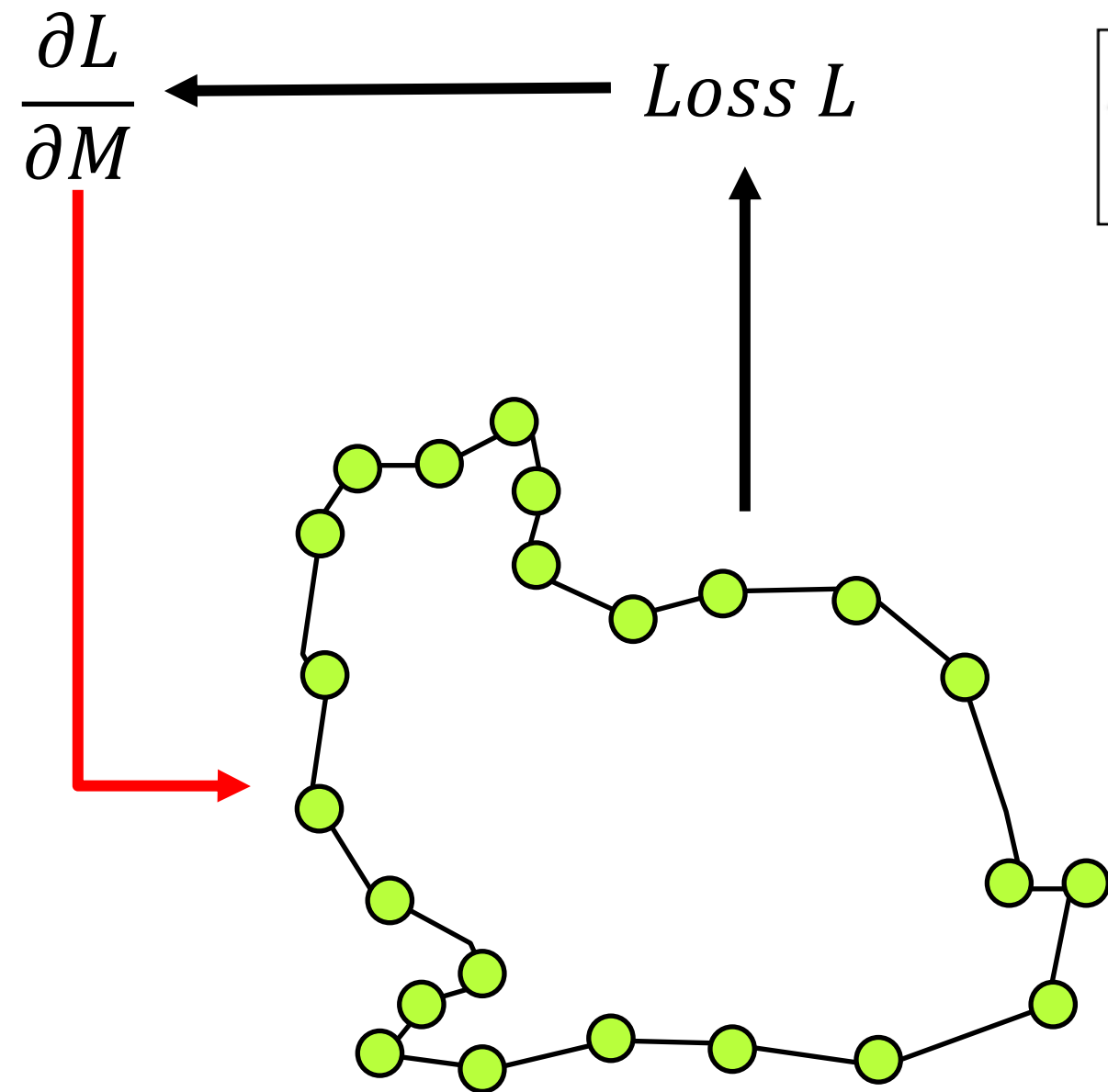
Loss L



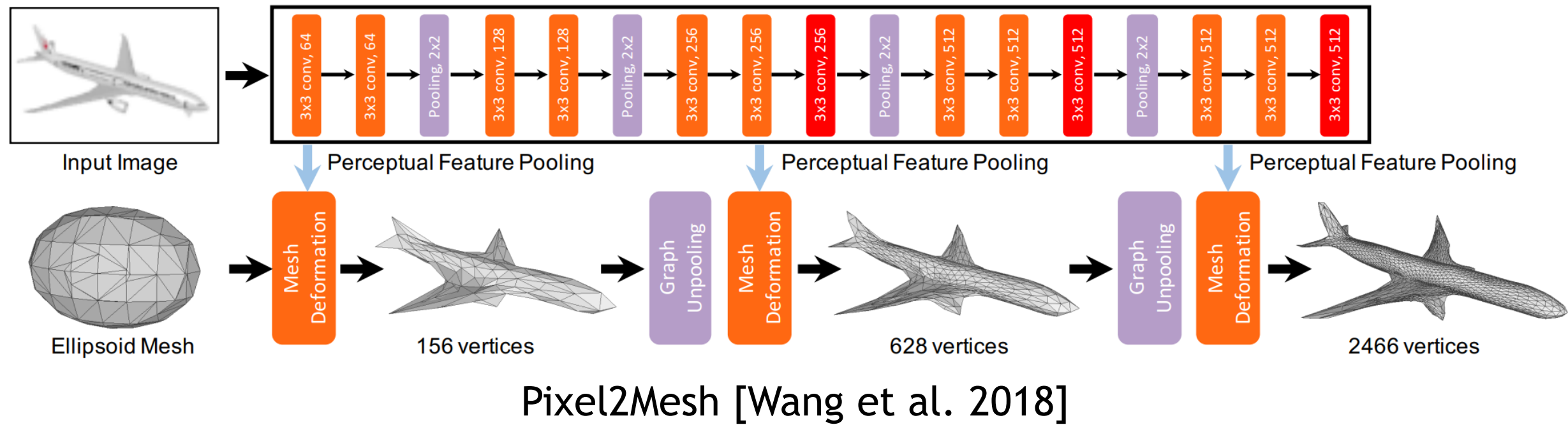
Surface Mesh
 $M = (V, F)$

GENERATING MESH VIA GRADIENT-BASED OPTIMIZATION

Why not directly optimizing the vertex positions of a mesh?



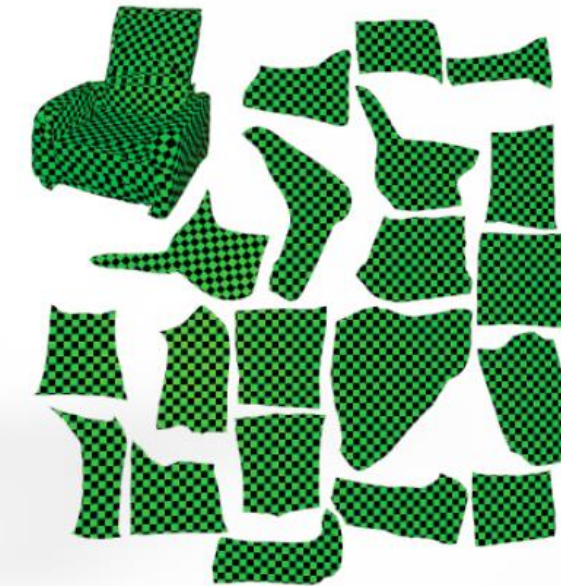
Surface Mesh
 $M = (V, F)$



(a) Possible Inputs



(b) Output Mesh from the 2D Image



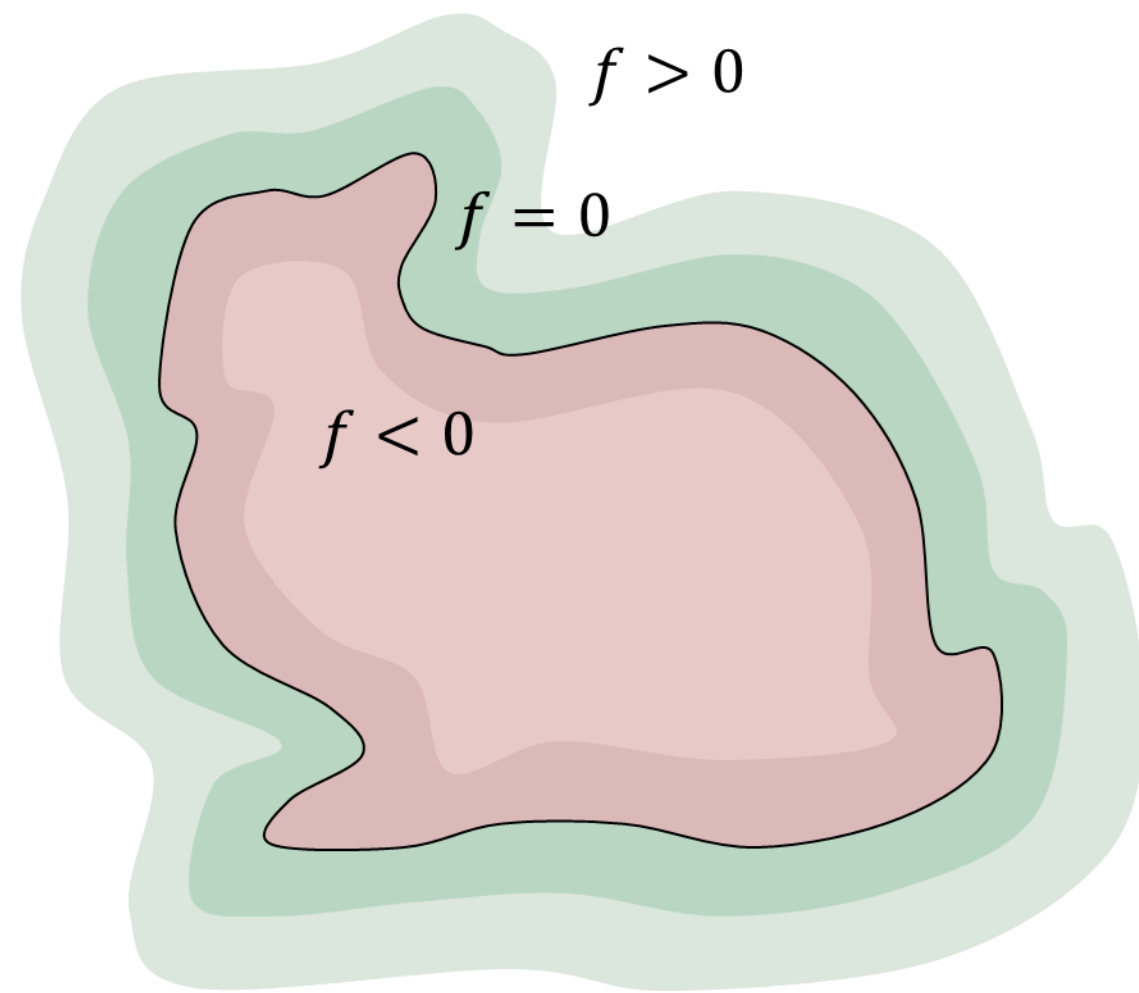
(c) Output Atlas (optimized)



(d) Textured Output

AtlasNet [Groueix et al. 2018]

GENERATING MESH VIA GRADIENT-BASED OPTIMIZATION



Scalar Field
 $f : \mathbb{R}^3 \rightarrow R$

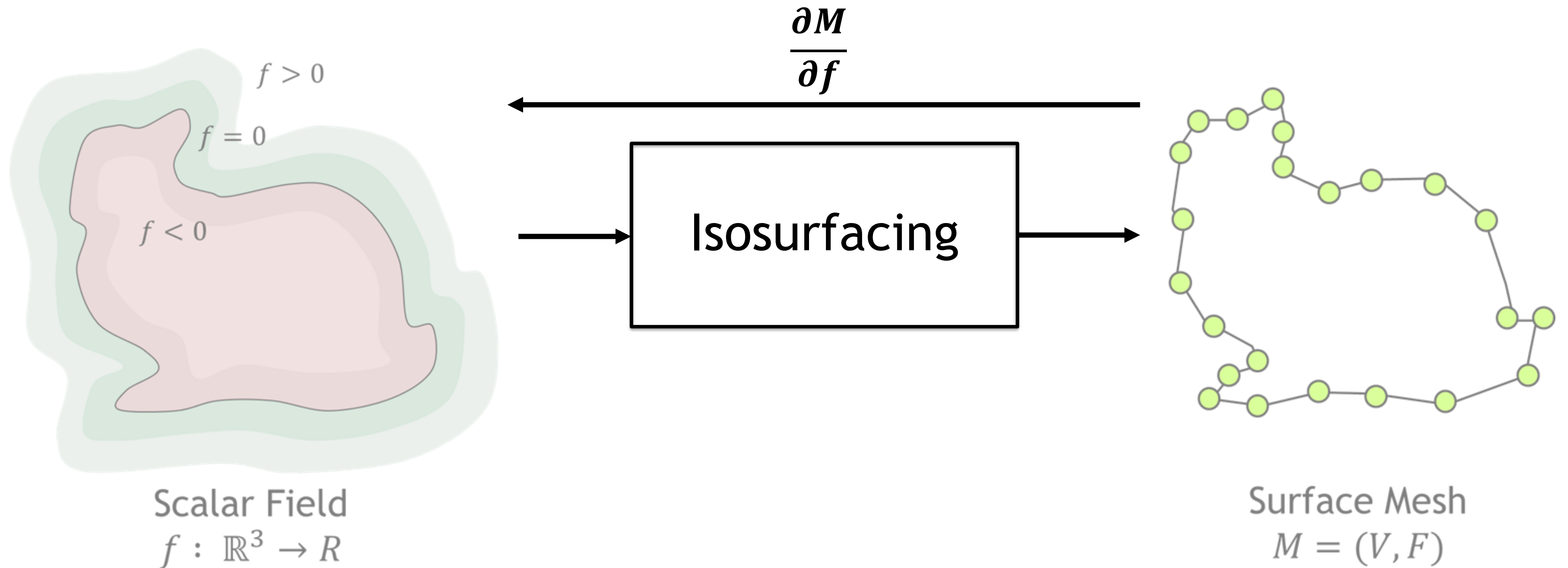
Using implicit field to parametrize surface:

- ✓ Support Arbitrary topology.
- ✓ Avoid topological errors.
- ✓ Easy for machine learning algorithms.

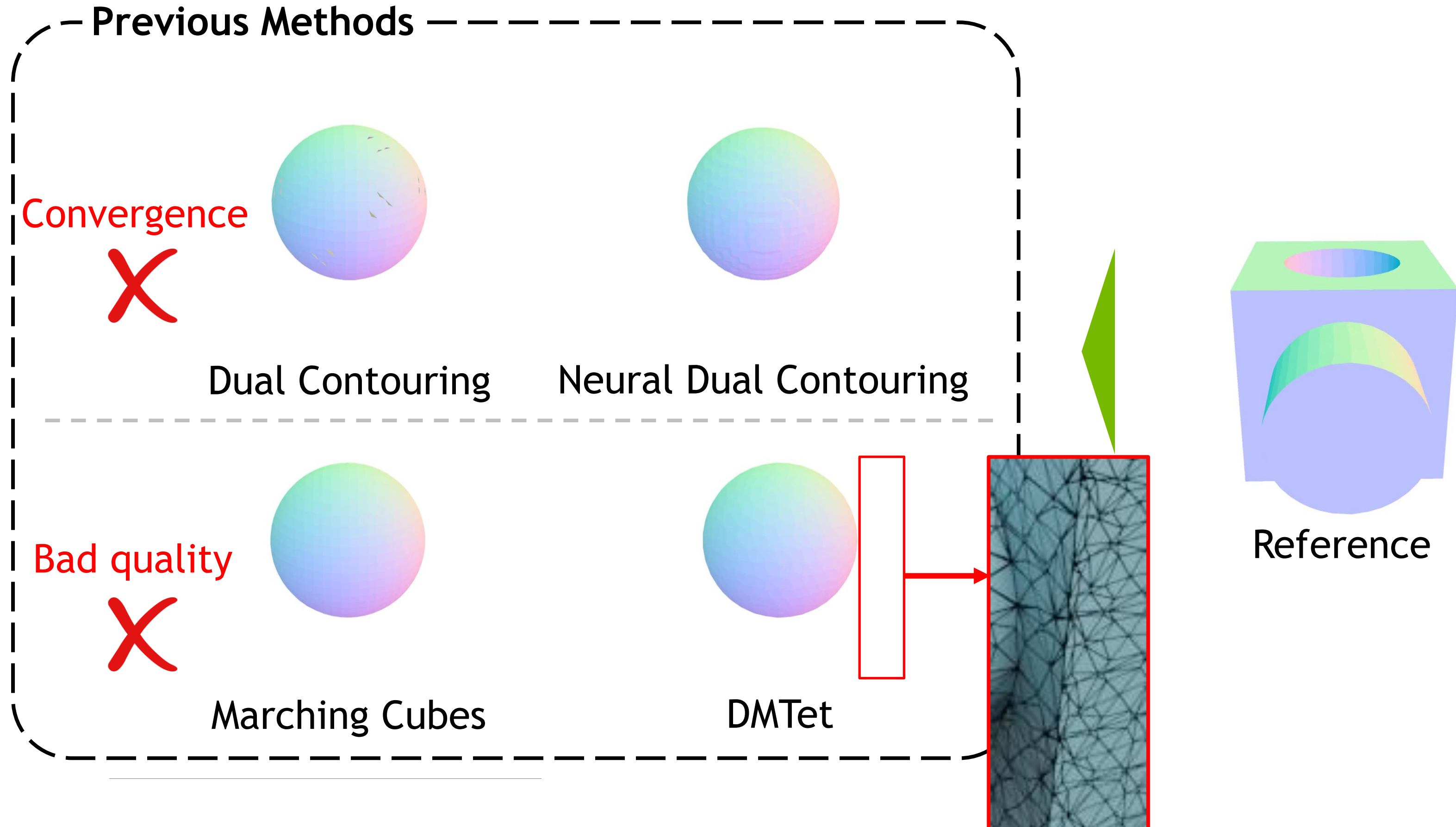
DESIRED ISOSURFACING METHOD

Accuracy + mesh quality.

Well-defined gradient differentiation.



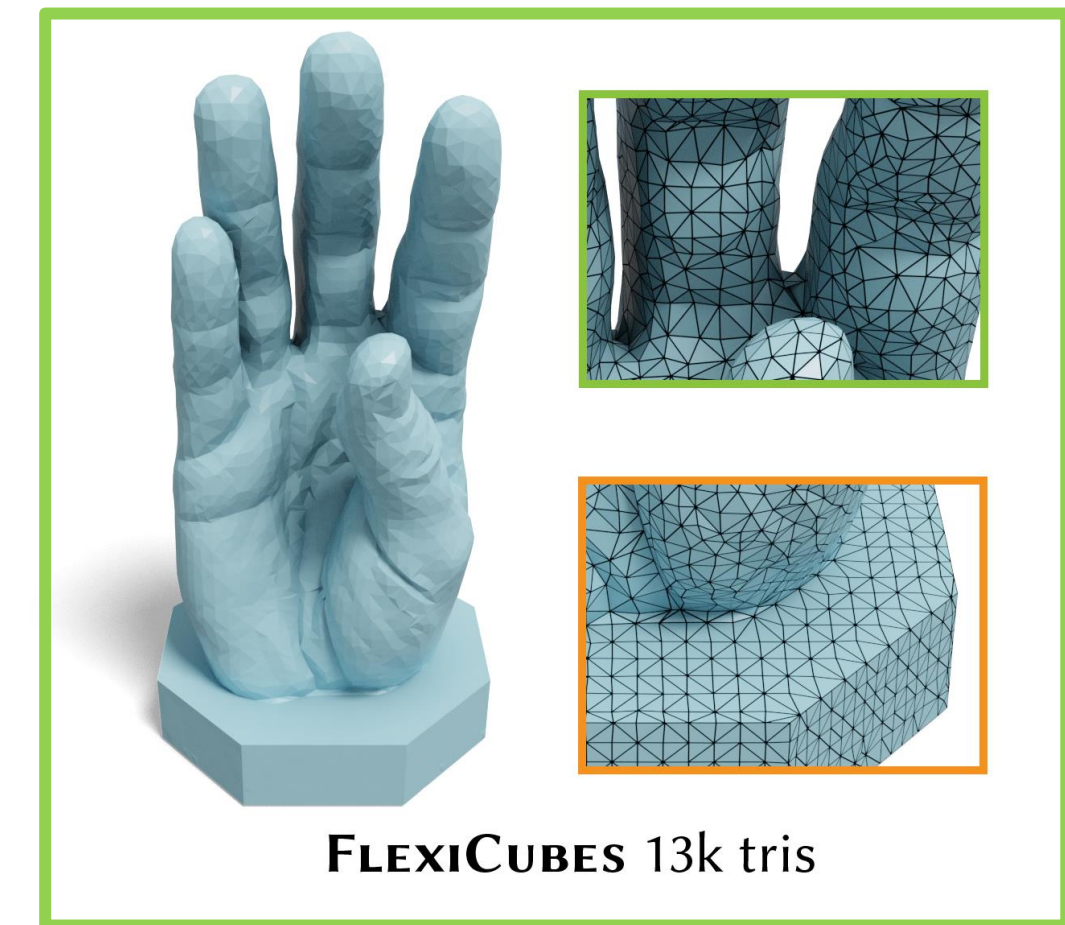
PREVIOUS METHODS FAIL TO SATISFY BOTH PROPERTIES



WE INTRODUCE FLEXICUBES



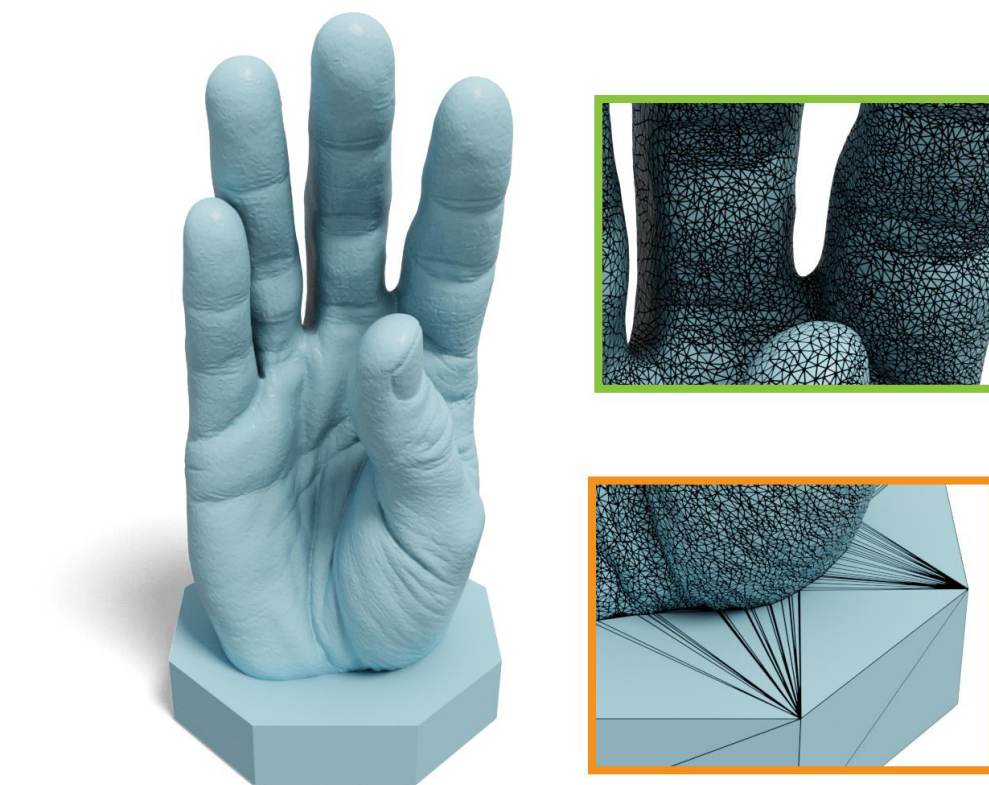
Marching Cubes 15k tris



FLEXICUBES 13k tris

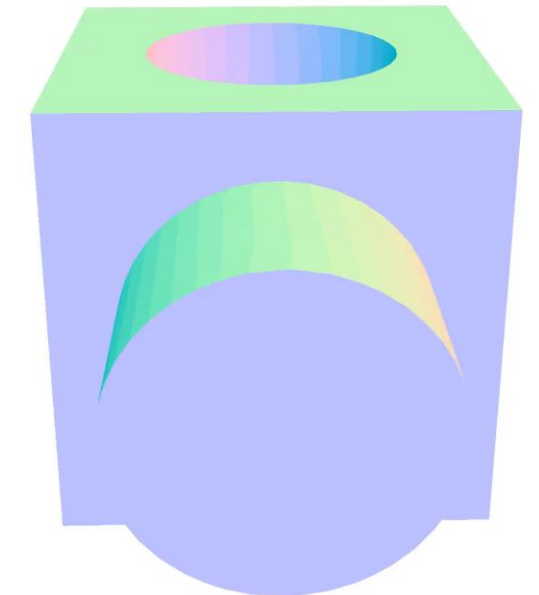


DMTET 15k tris

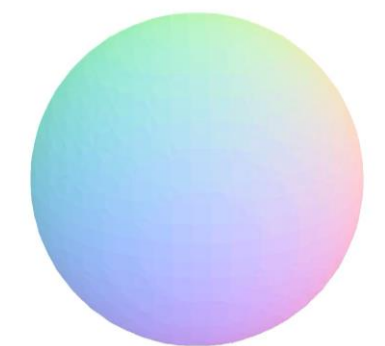


Reference 91k tris

- ✓ High-fidelity
- ✓ Good Quality
- ✓ Convergence →

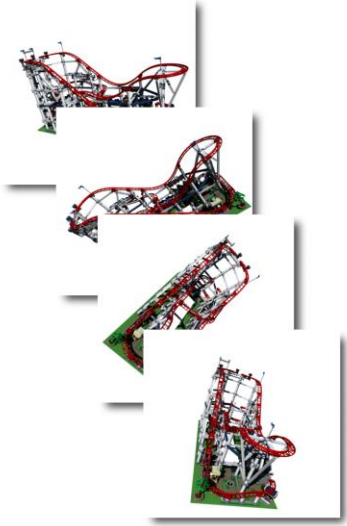


Reference



FlexiCubes

APPLICATIONS W/ FLEXICUBES



3D Reconstruction from Images



Generative 3D Modeling



Mesh Regularizations



Animated 3D Reconstruction



Physics Simulation

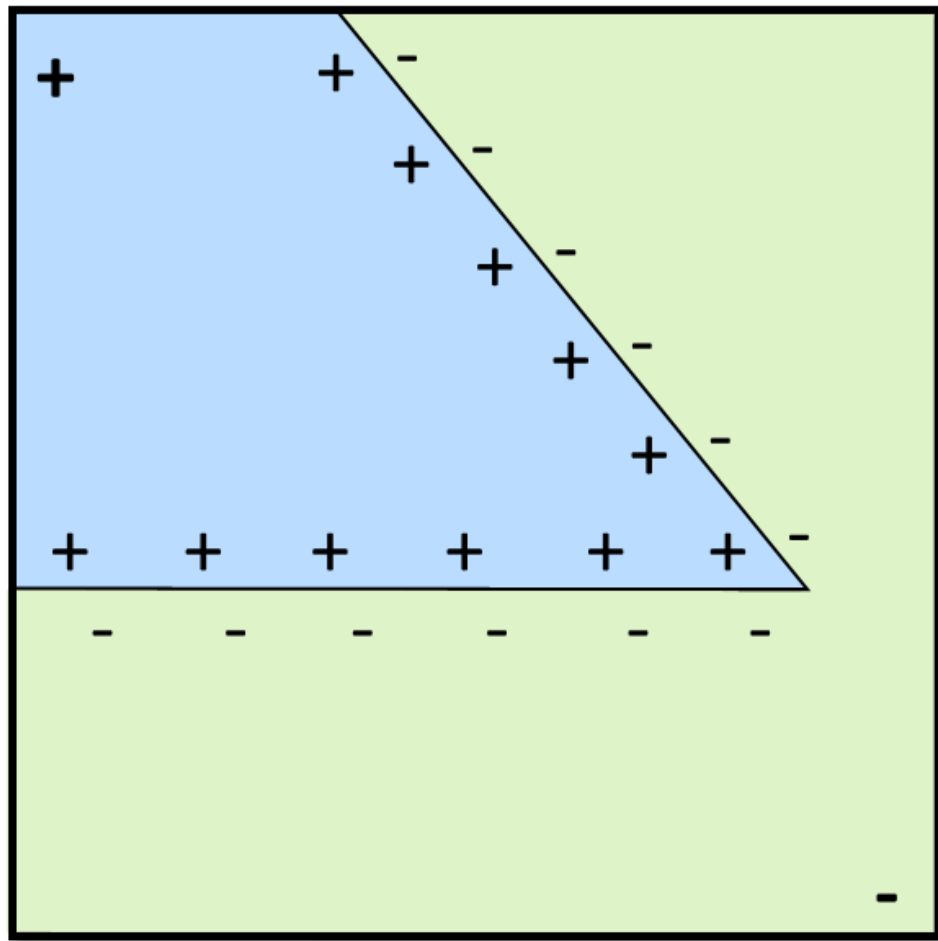
... and more!

WHY IS PRIOR WORK NOT SUFFICIENT?

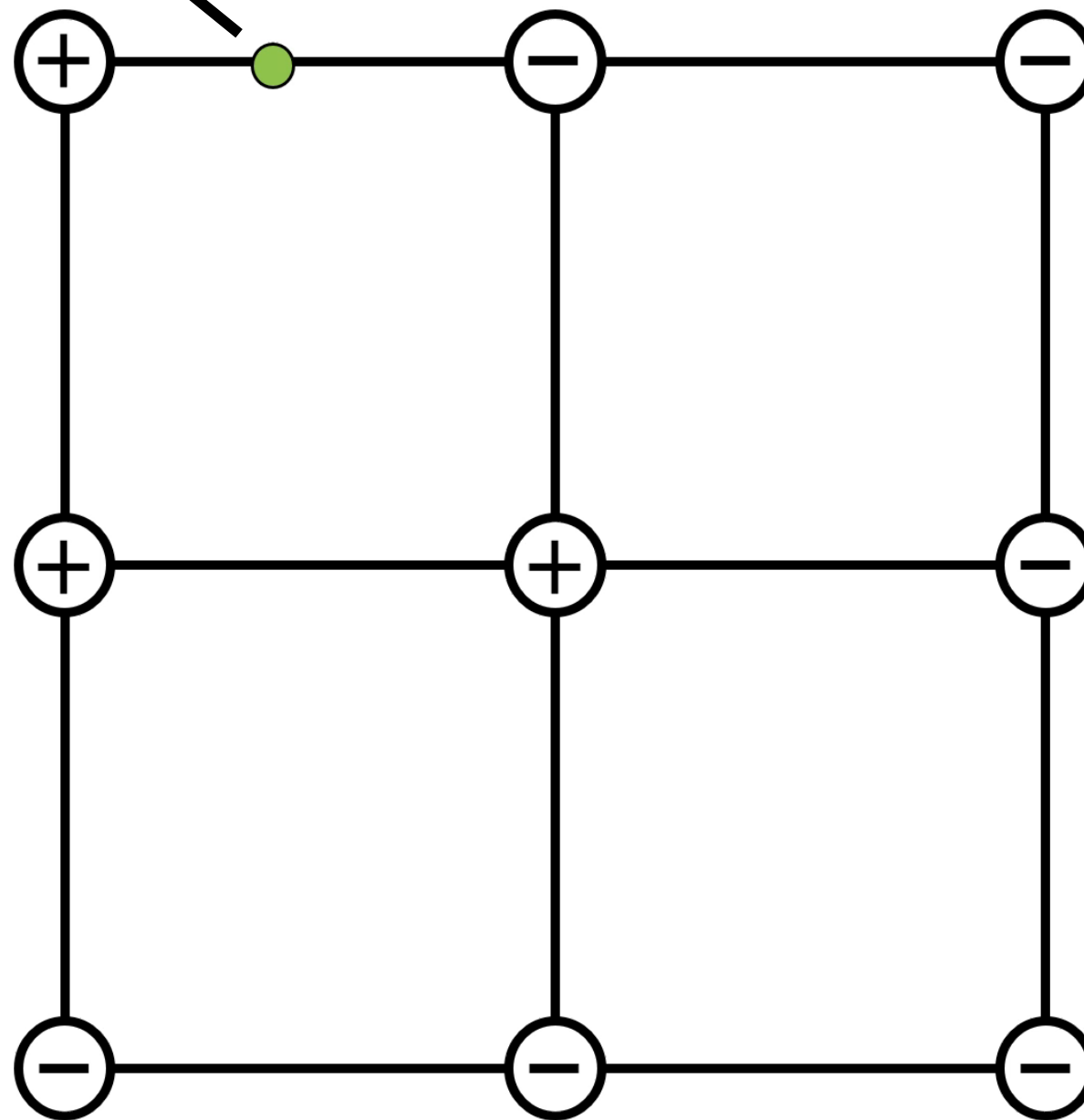
MARCHING CUBES

SDF \leftarrow $vertex\ position$

zero crossing: $u_e = \frac{s(x_i)x_j - s(x_j)x_i}{s(x_i) - s(x_j)}$ ✗ Mesh vertices are constrained on lattice edges.

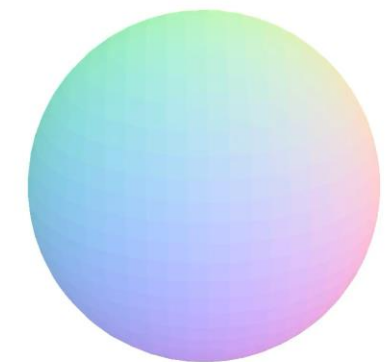
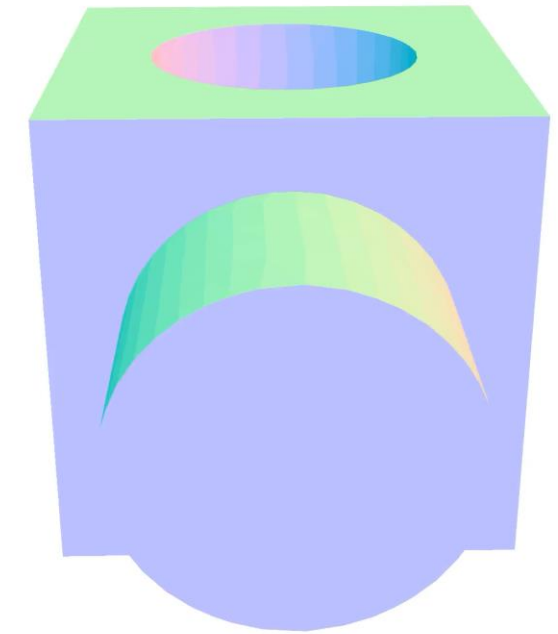


Signed Distance Field



Marching Cubes

Ground Truth



✓ Grad.

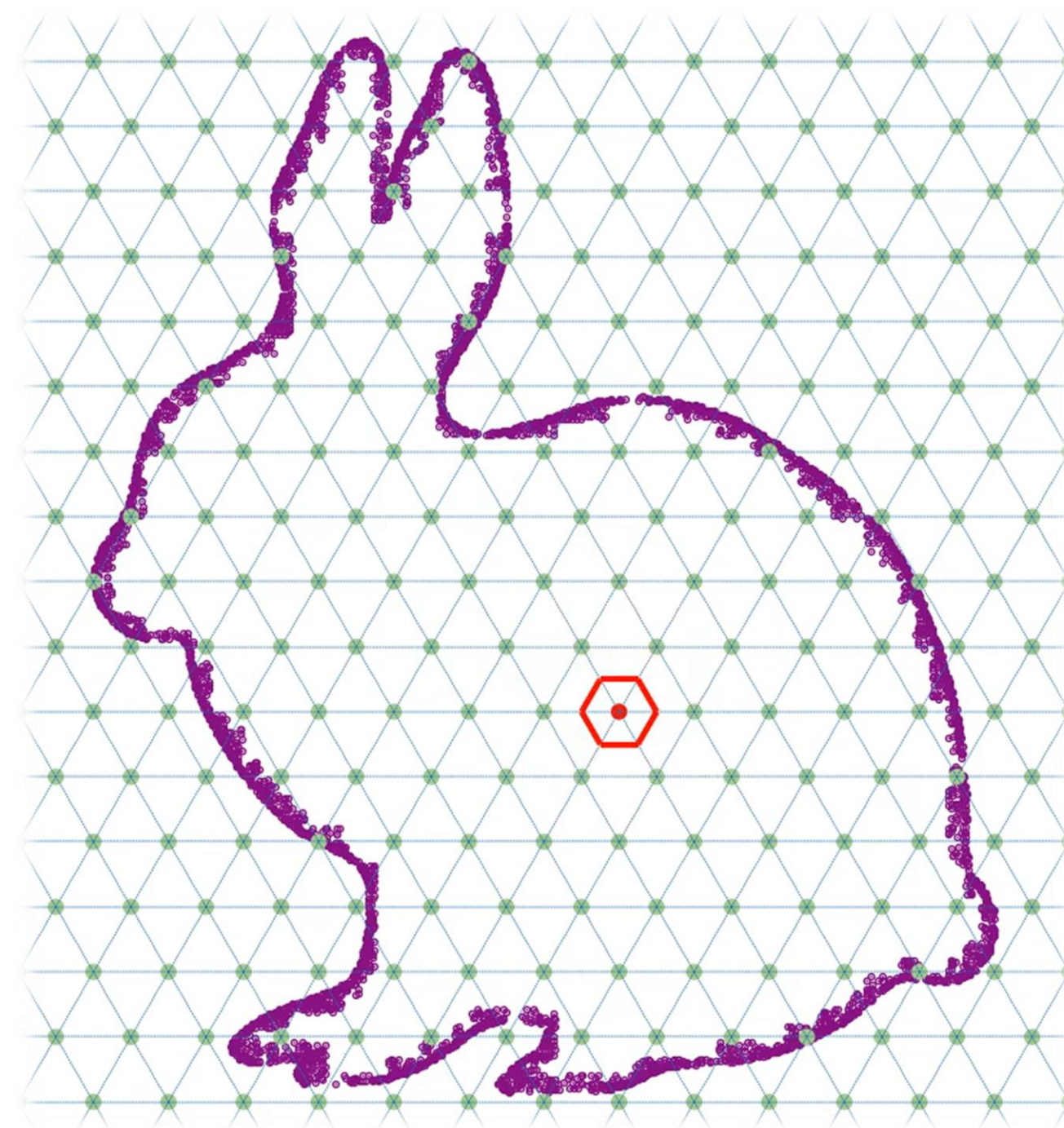
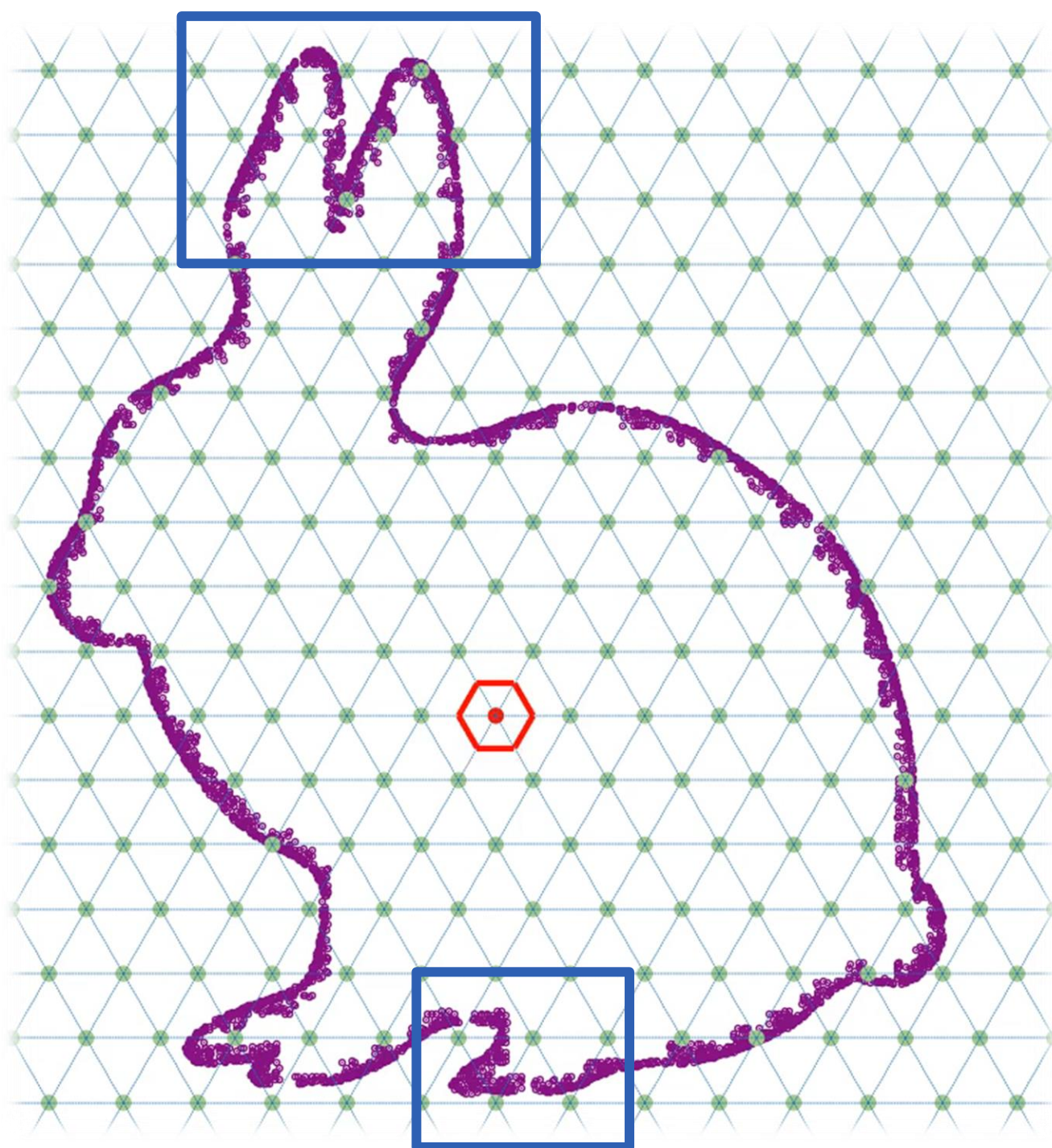
DEEP MARCHING TETRAHEDRA (DMTET)

SDF ← $vertex\ position$

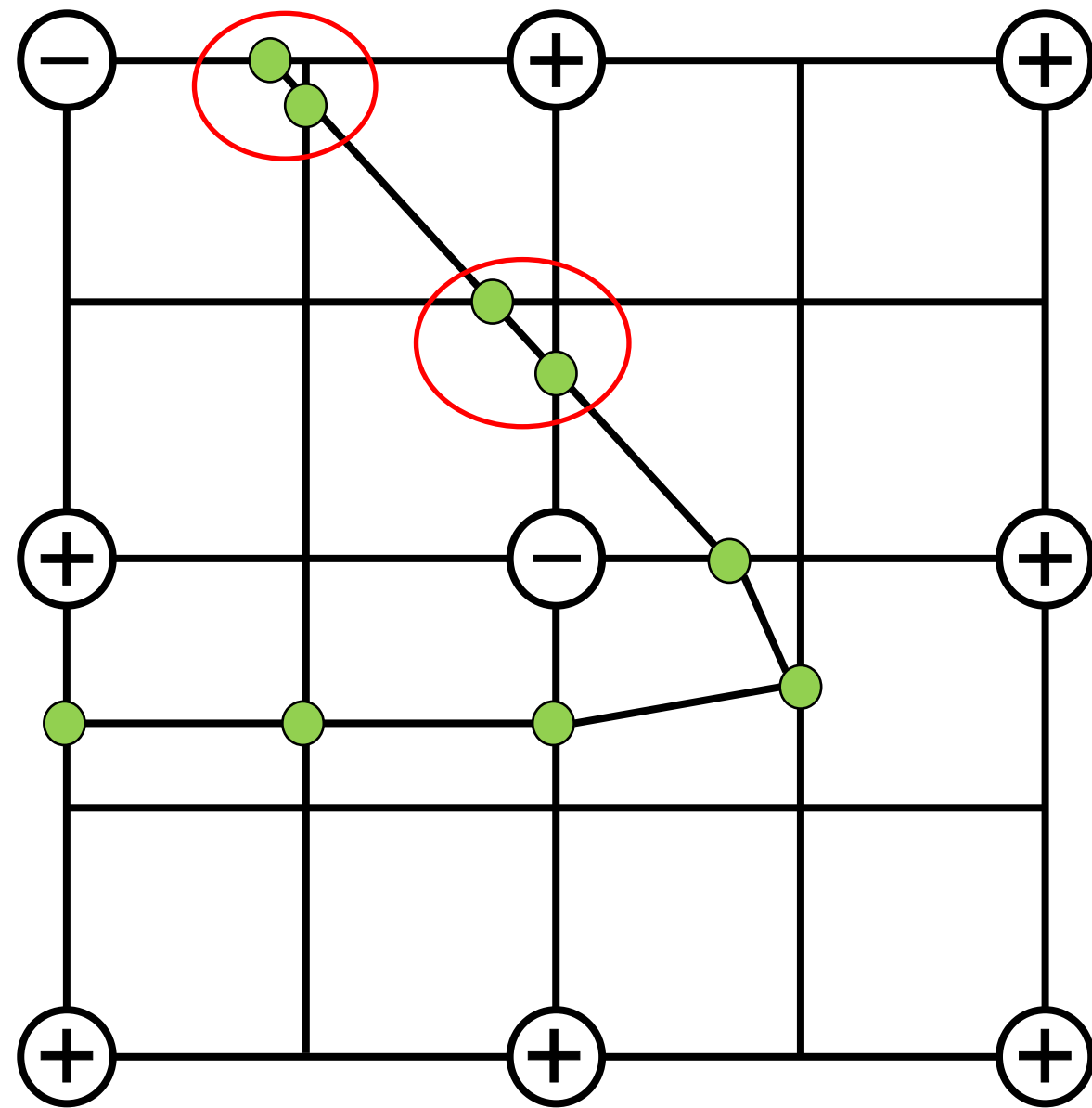
$$zero\ crossing: u_e = \frac{s(x_i)x_j - s(x_j)x_i}{s(x_i) - s(x_j)}$$

— Extracted Surface

⋯ GT Points



MARCHING CUBES



Increase grid resolution

Not ideal for optimization settings.



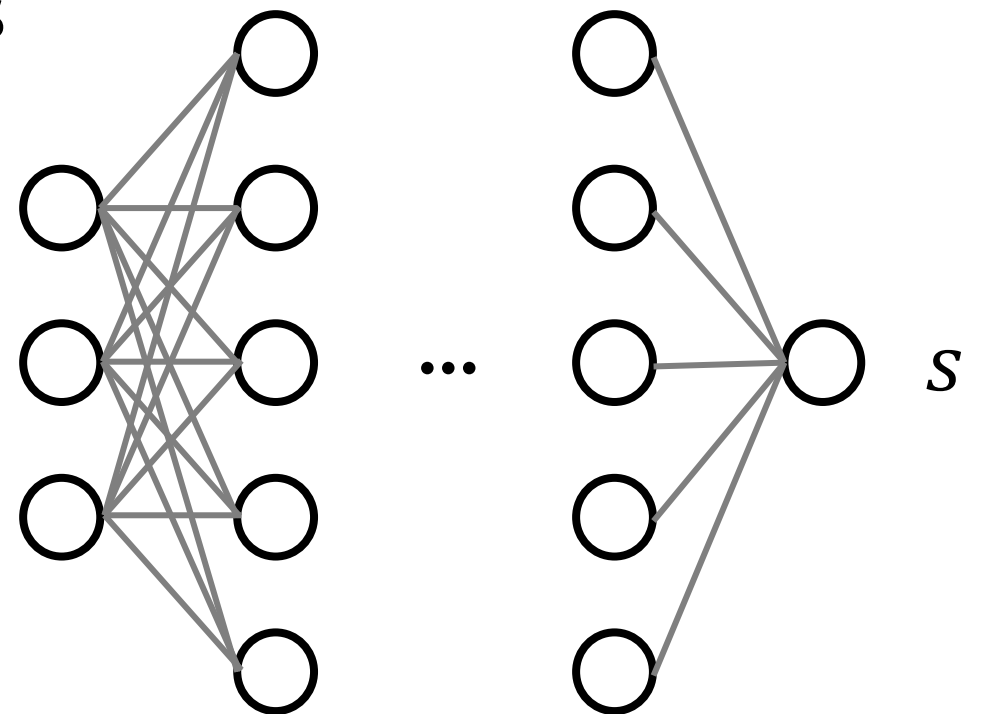
✗ Excessive number of triangles
-> bad for downstream applications.

✗ Requires more SDF samples at every optimization step.

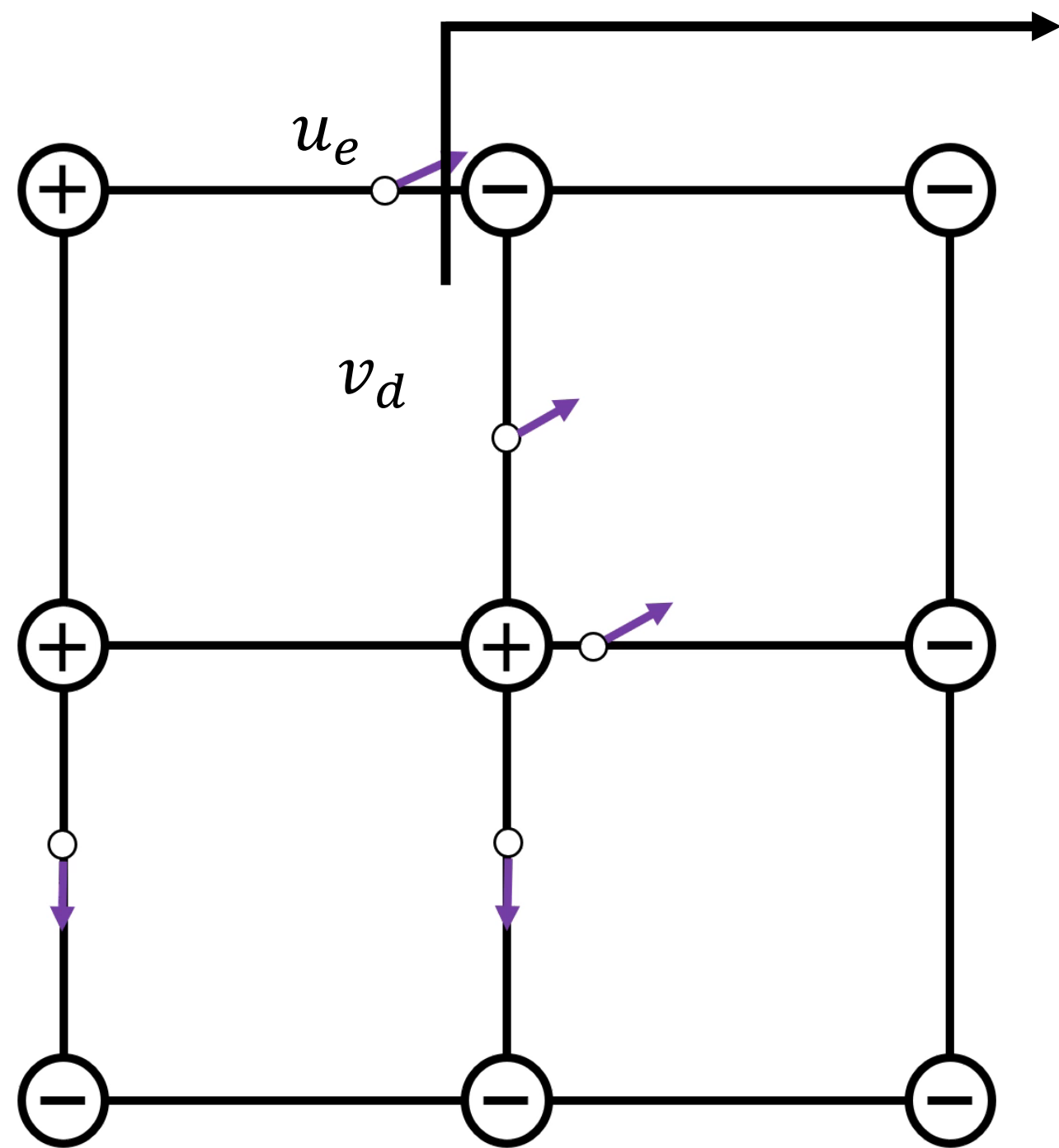
Especially for neural implicits
s.t.

$$s = f_{\theta}(x)$$

$$x \in \mathbb{R}^3$$



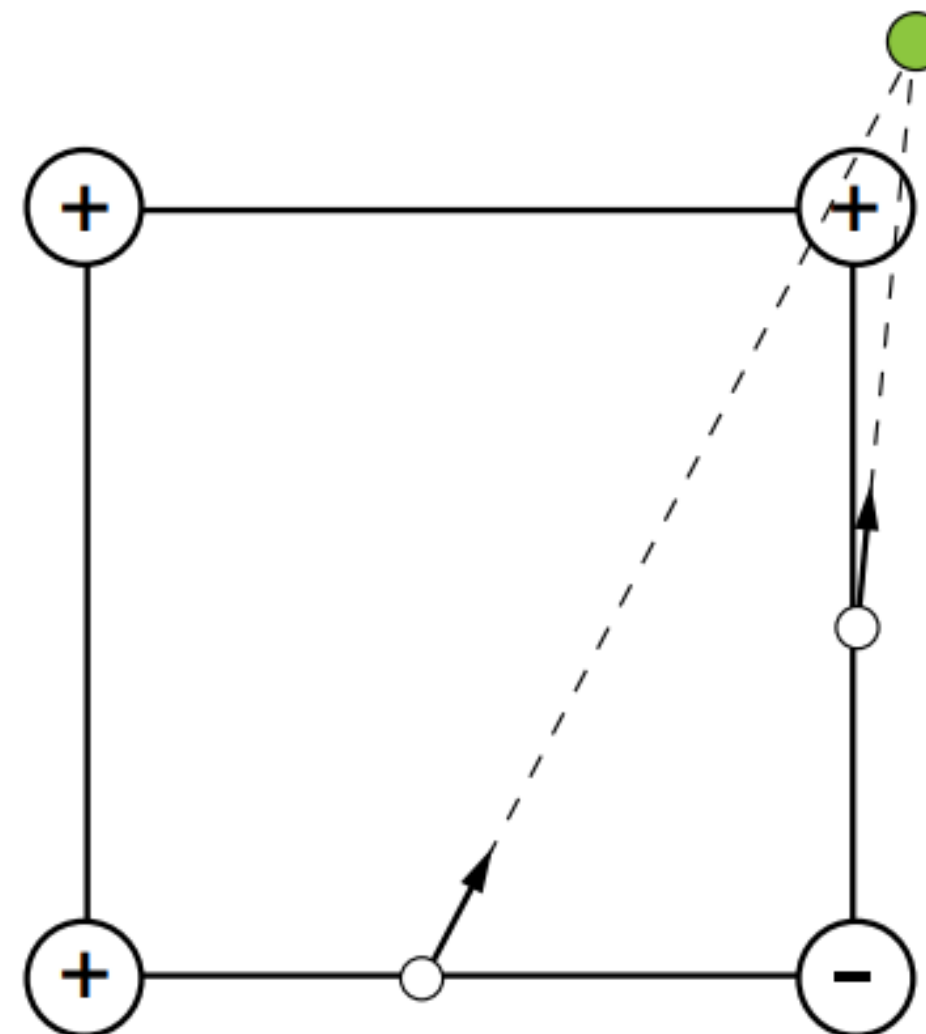
DUAL CONTOURING



Dual Contouring

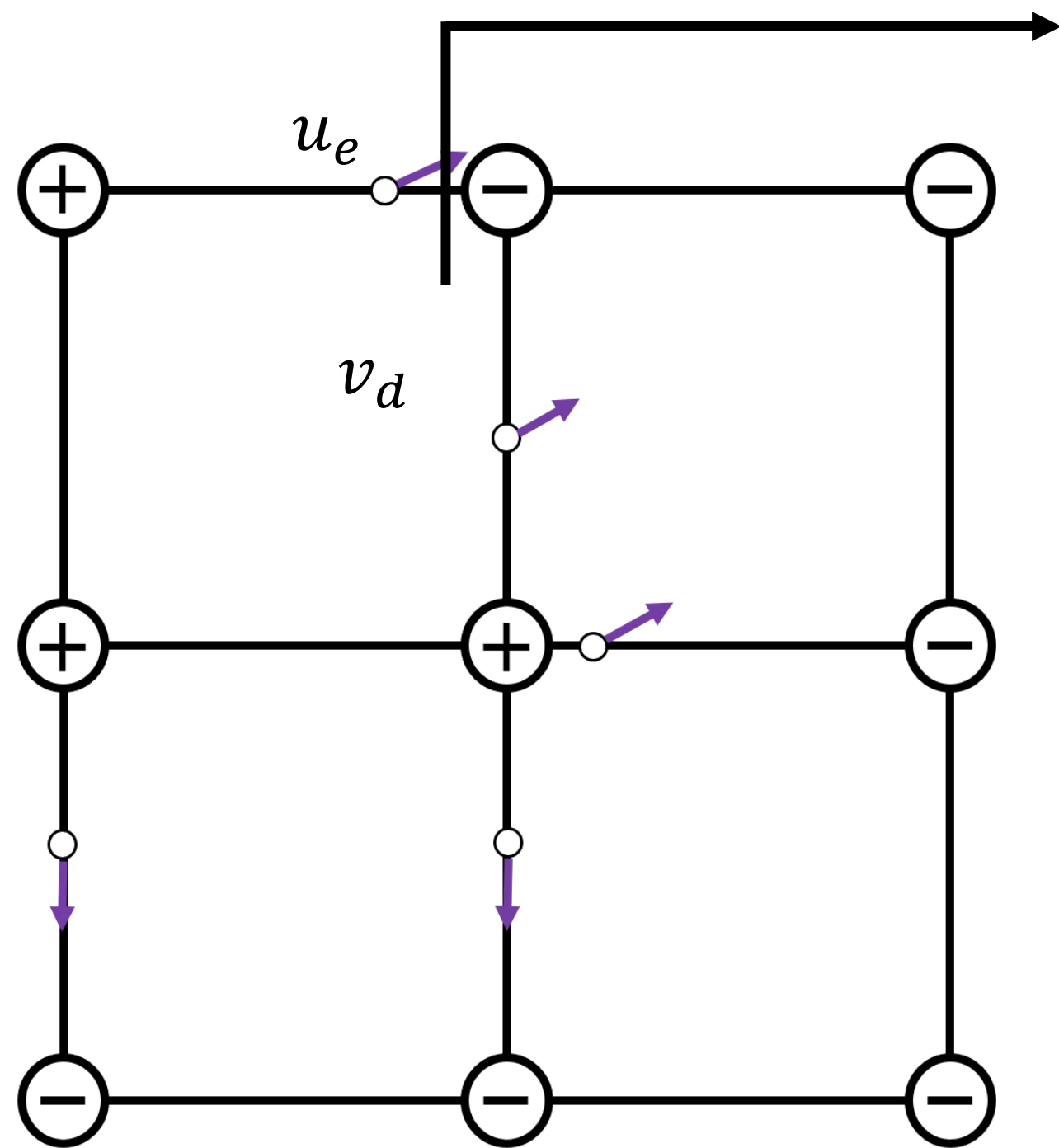
$$v_d = \operatorname{argmin}_{v_d} \sum_{u_e \in \mathcal{Z}_e} \nabla s(u_e) \cdot (v_d - u_e)$$

- ✓ Vertex placement is more adaptive to surface feature.
- ✗ Grad. issue due to singularity in QEF.



Degenerated config. in DC

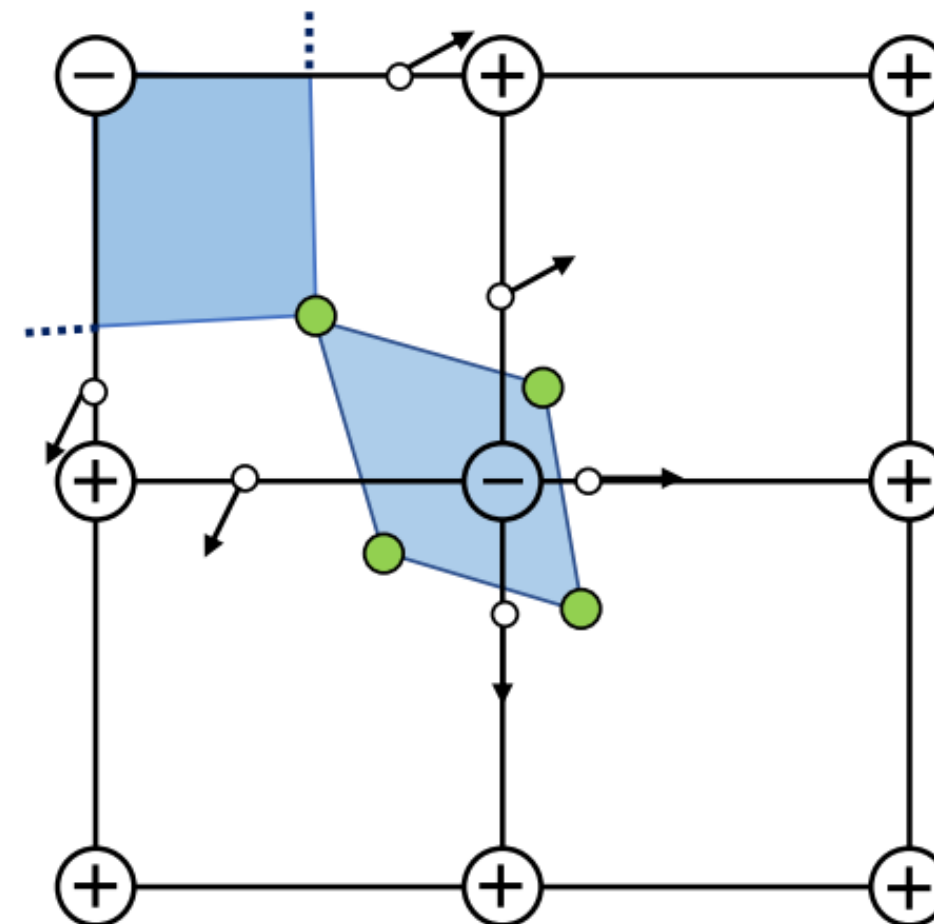
DUAL CONTOURING



Dual Contouring

$$v_d = \operatorname{argmin}_{v_d} \sum_{u_e \in \mathcal{Z}_e} \nabla s(u_e) \cdot (v_d - u_e)$$

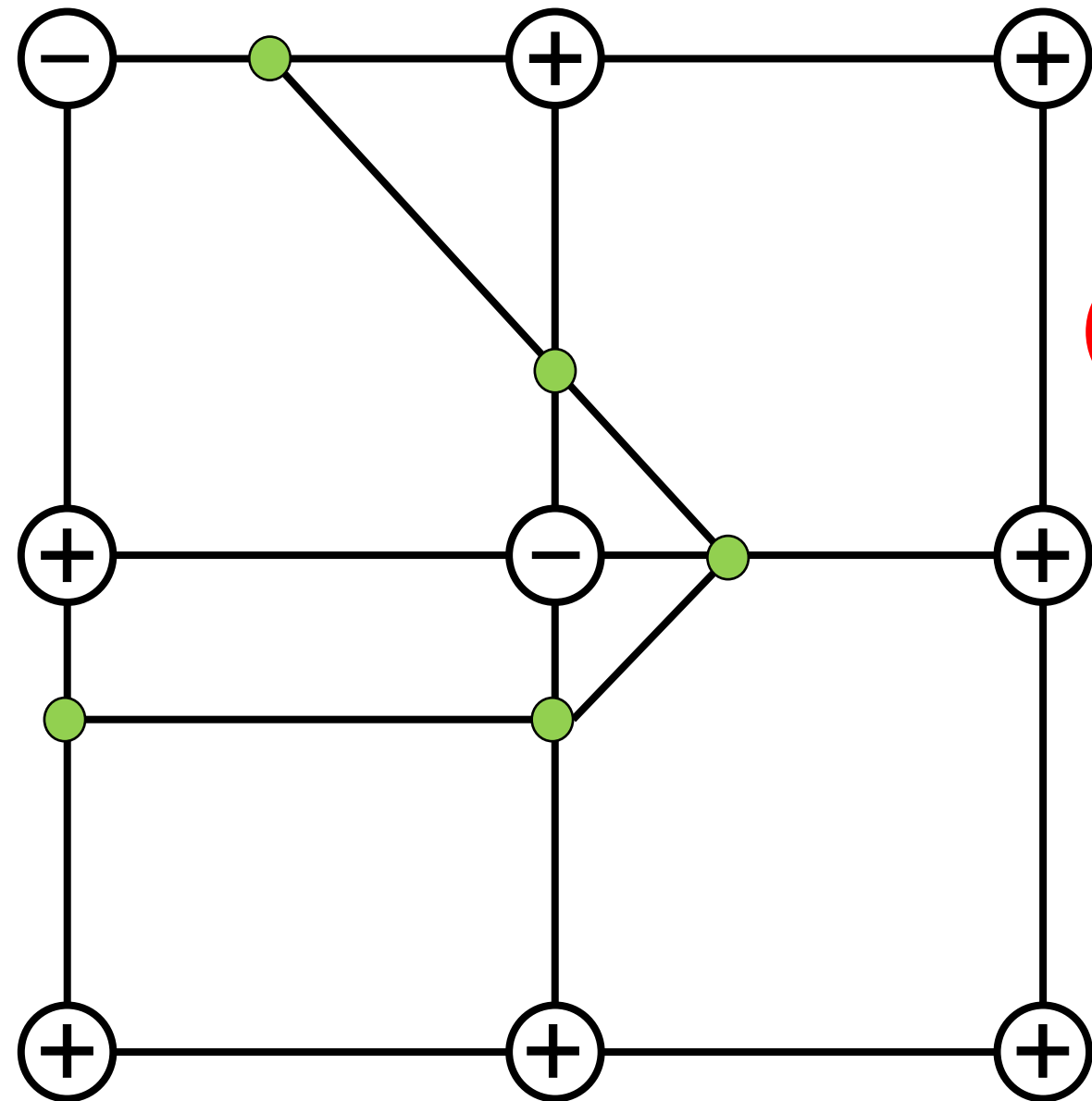
- ✓ Vertex placement is more adaptive to surface feature.
- ✗ Grad. issue due to singularity in QEF.
- ✗ Produce non-manifold results



OUR FORMULATIONS

MAIN IDEA

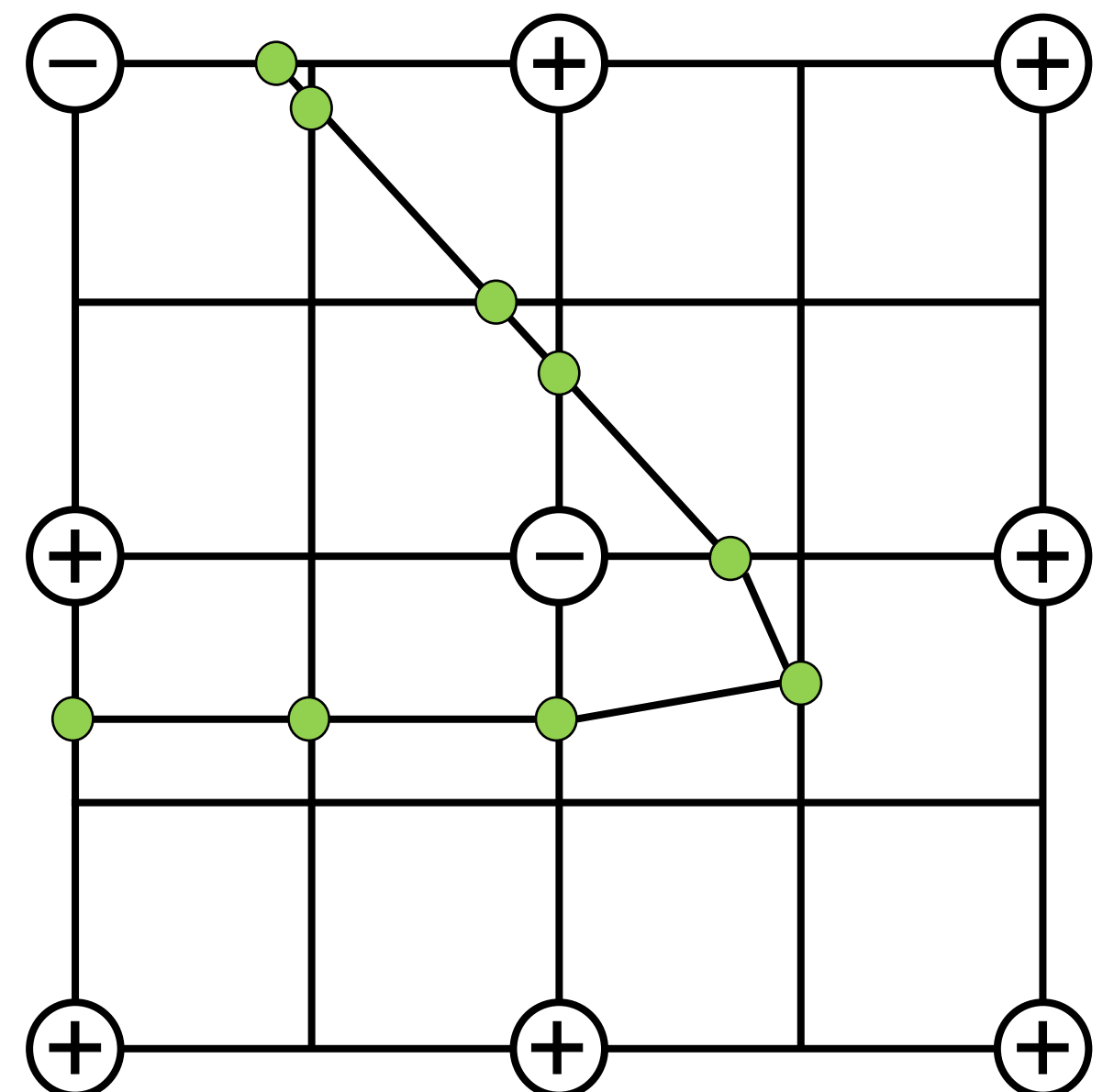
Improve fitting with more elements?



Marching Cubes



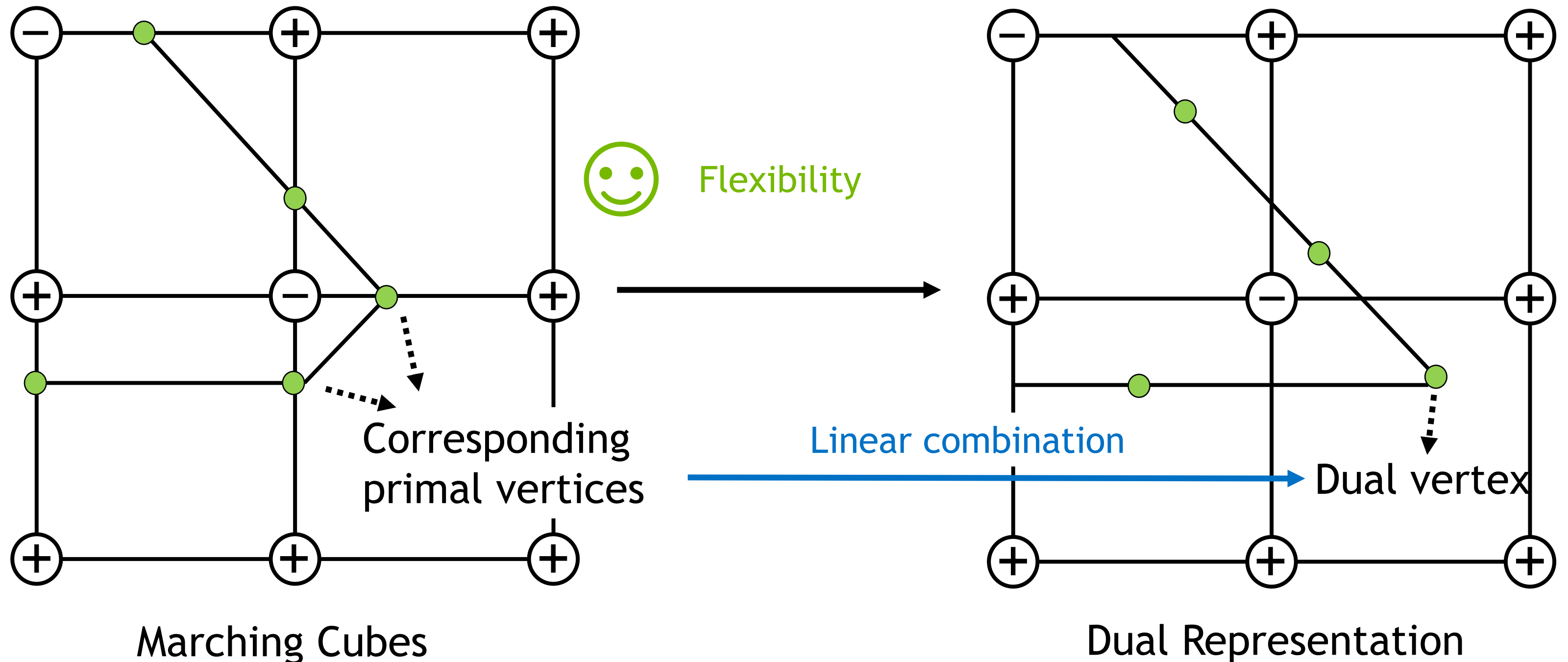
More SDF quires.
More vertices.
More triangles.



MAIN IDEA

Improve fitting with ~~more elements?~~ **additional flexibility!**

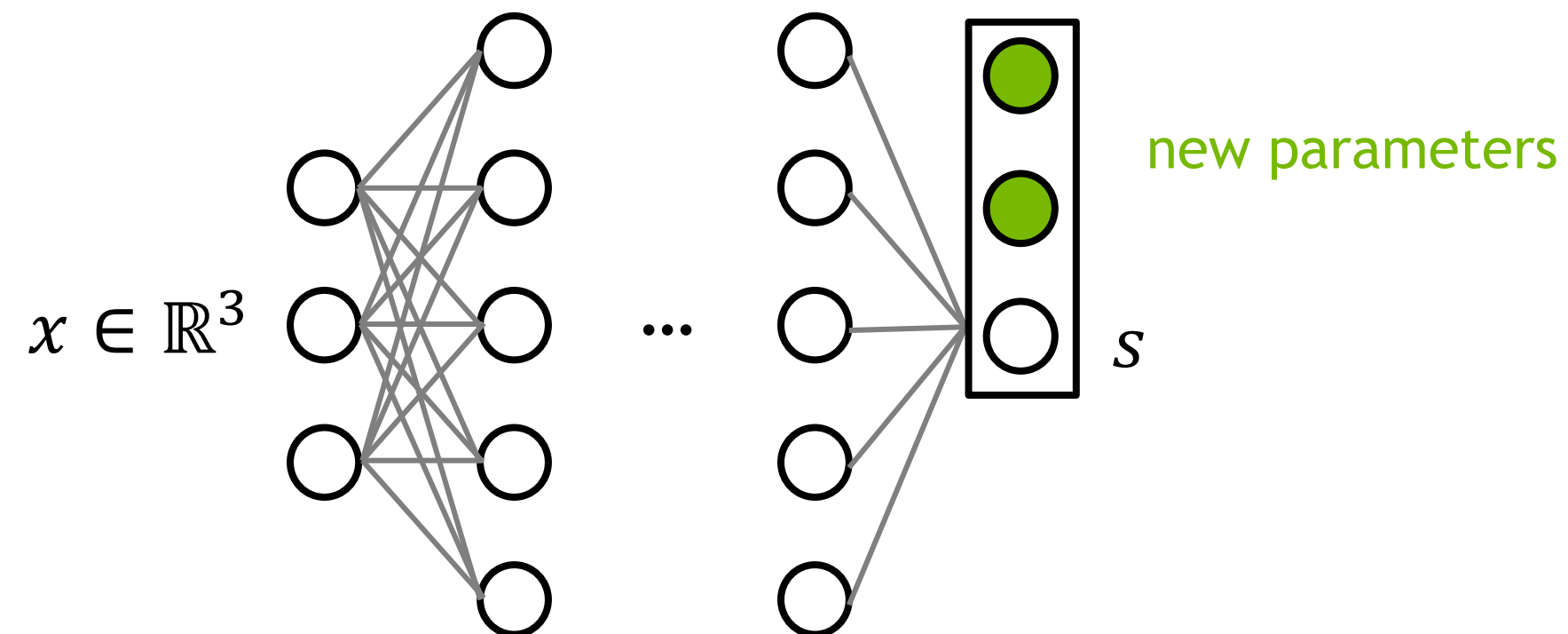
Recall prior dual methods **diverge** during optimization.



OUR FORMULATIONS

We introduce 3 types of parameters into Dual Marching Cubes:

- Interpolation weights to position dual vertices in space.
- Splitting weights to control how to split quadrilaterals into triangles.
- Deformation vector for spatial alignment.

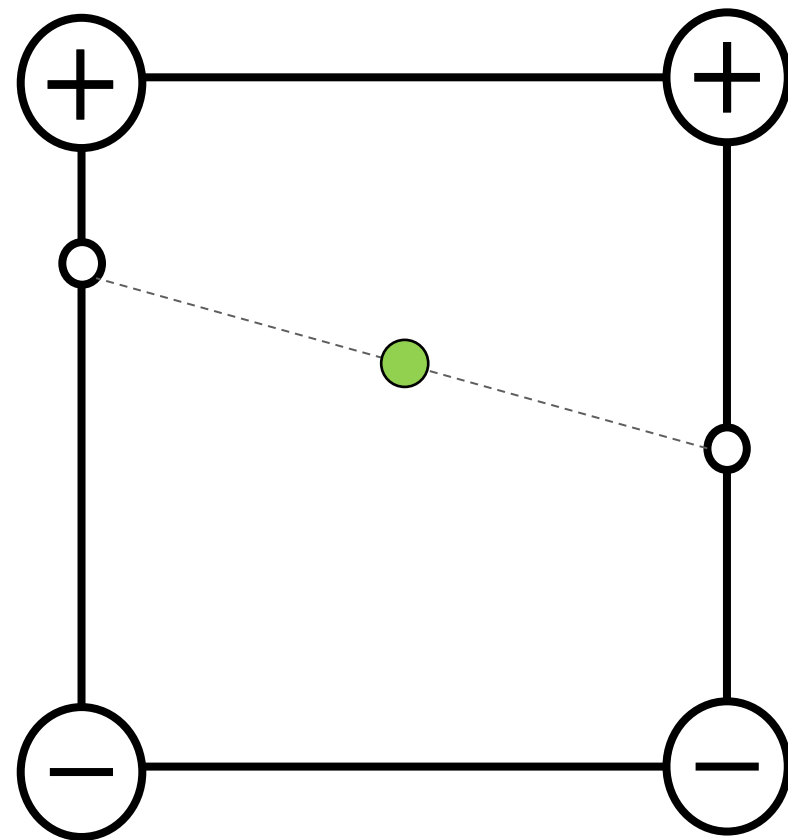


- ✓ Appended as additional output channel in neural implicit.

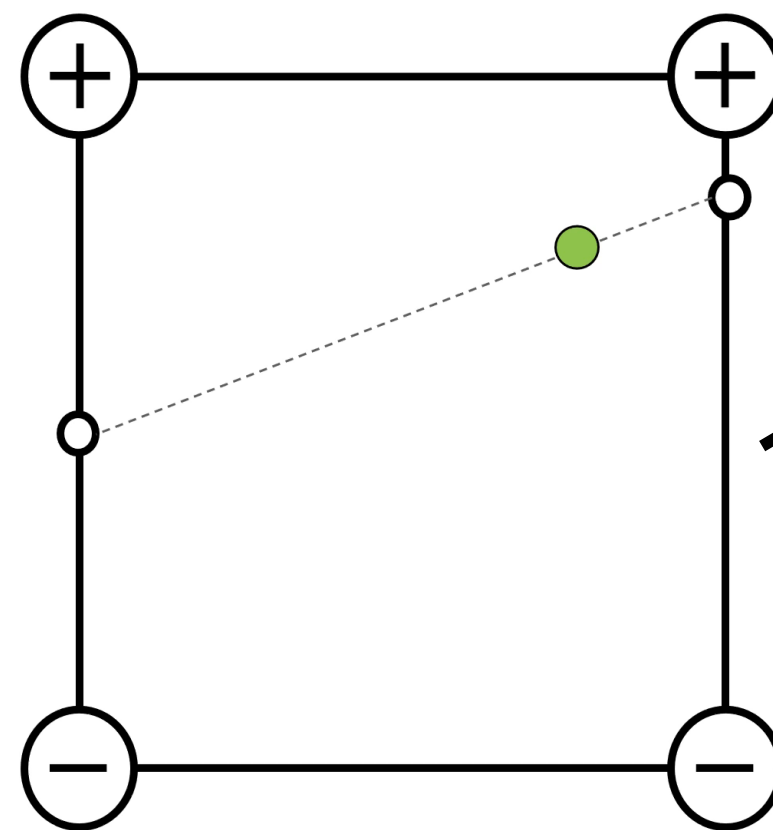
OUR FORMULATION

Interpolation weights:

- α per-cell adjusting interpolation along each edge.



Centroid



With α

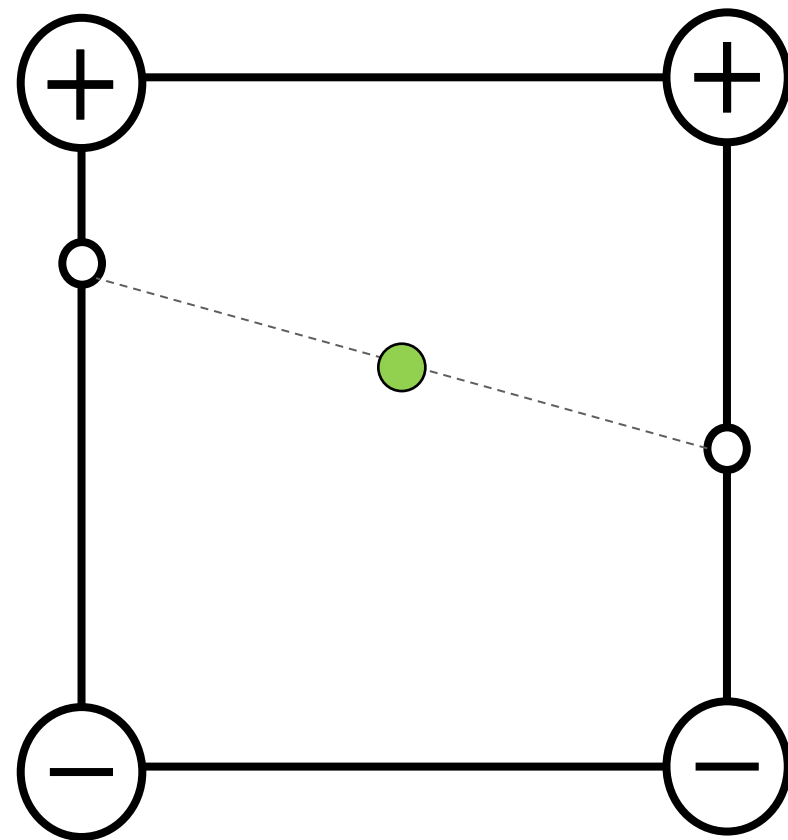
Linear interpolation:

$$u_e = \frac{\alpha_i s(x_i) x_j - \alpha_j s(x_j) x_i}{\alpha_i s(x_i) - \alpha_j s(x_j)}$$

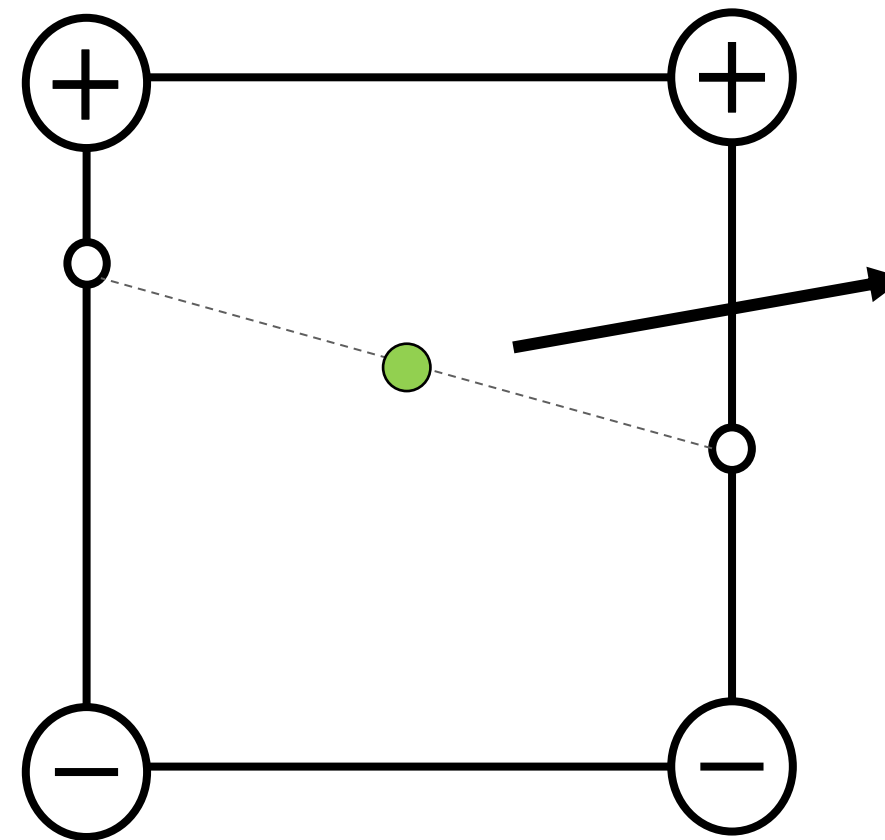
OUR FORMULATION

Interpolation weights:

- α per-cell adjusting interpolation along each edge.
- β per-cell adjusting vertex position within each dual face



Centroid



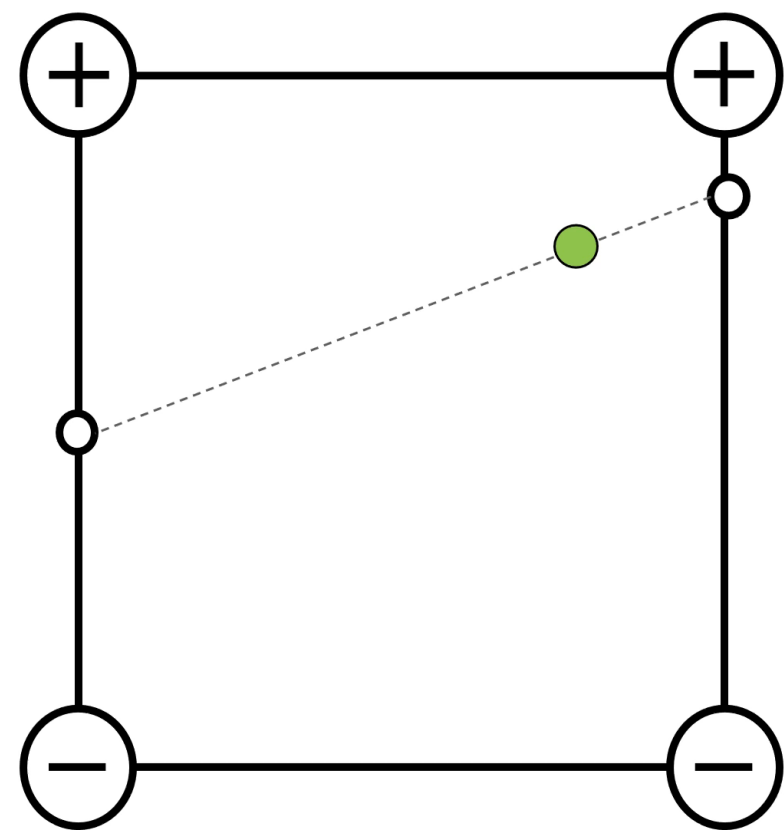
With β

Weighted average:

$$v_d = \frac{1}{\sum_{u_e \in V_E} \beta_e} \sum \beta_e u_e$$

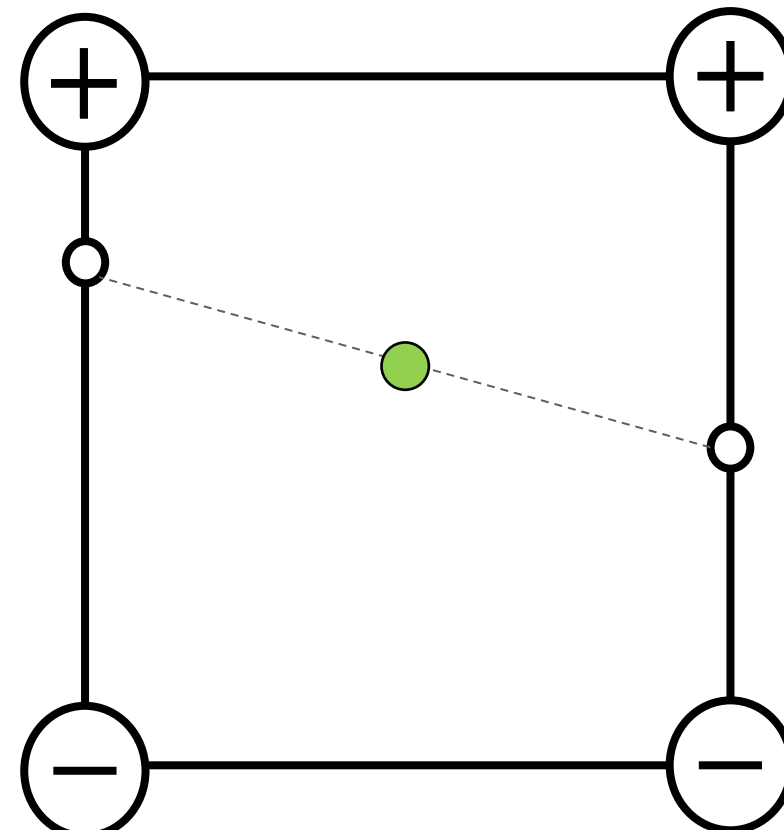
INTERPOLATION WEIGHTS

- α per-cell adjusting interpolation along each edge.
 - β per-cell adjusting vertex position within each dual face
- Convex combinations



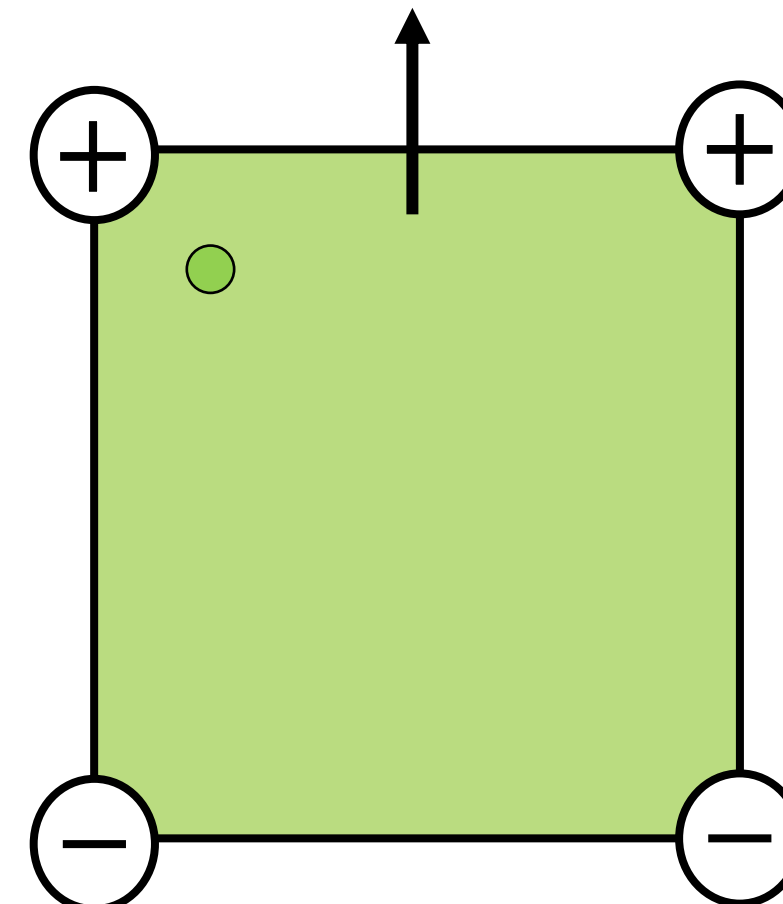
With α

+



With β

=

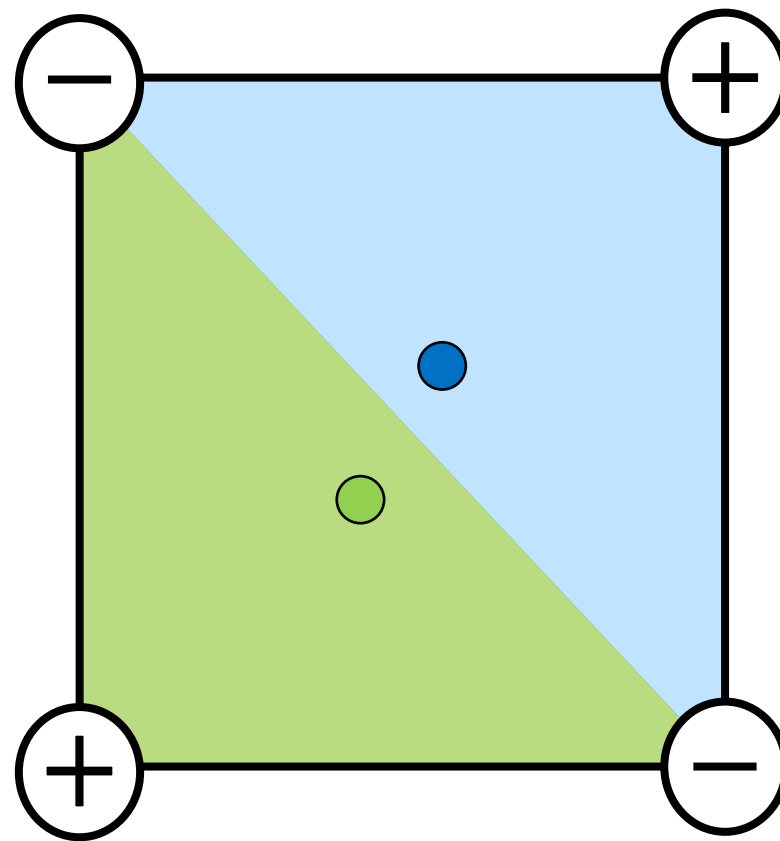


Movable regions of the dual vertex.

INTERPOLATION WEIGHTS

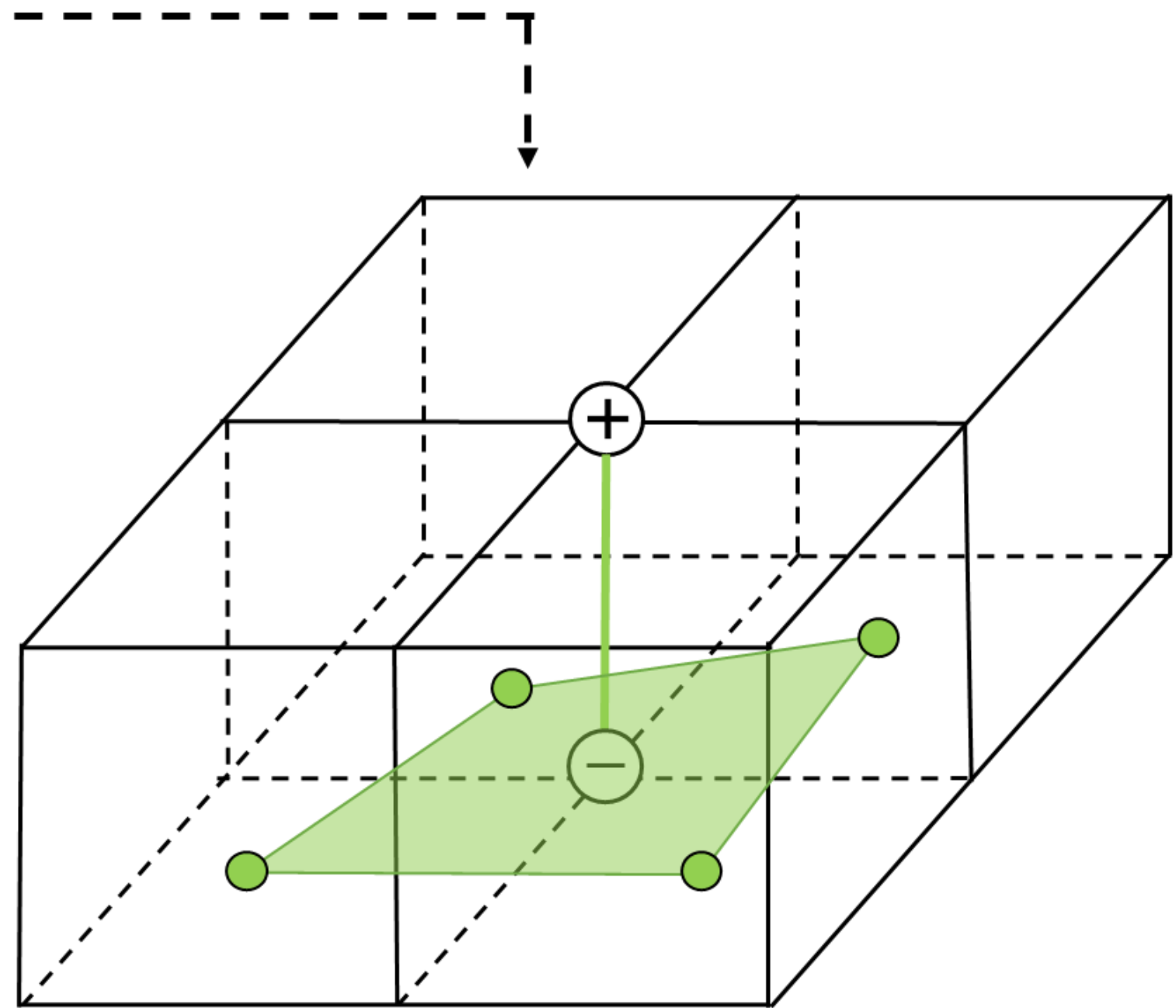
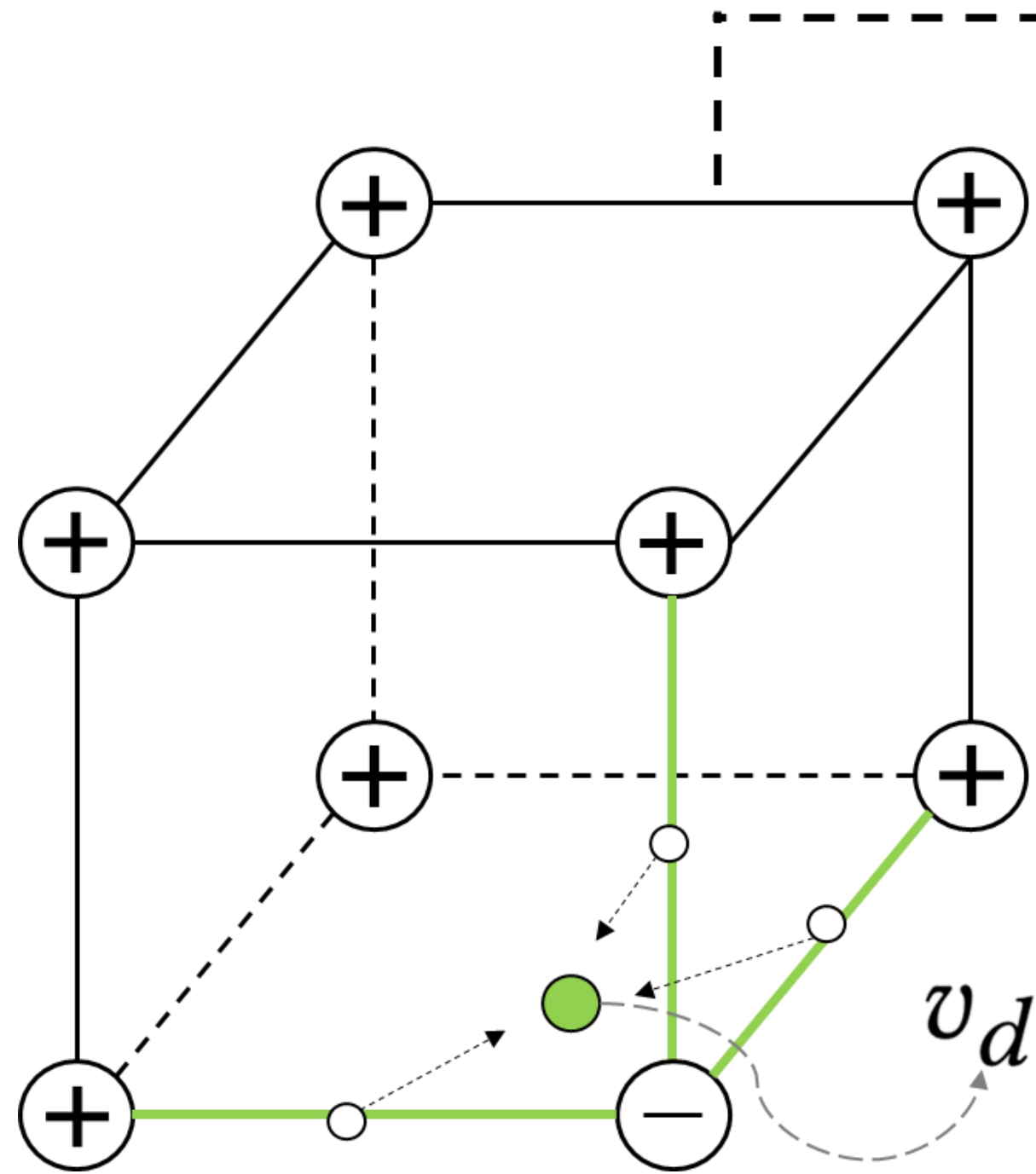
- α per-cell adjusting interpolation along each edge.
- β per-cell adjusting vertex position within each dual face

$\alpha, \beta \in \mathbb{R}^+$ → ✓ Preserves grad.



- ✓ When a cell emits multiple dual vertices, they lie in non-overlapping convex hulls.

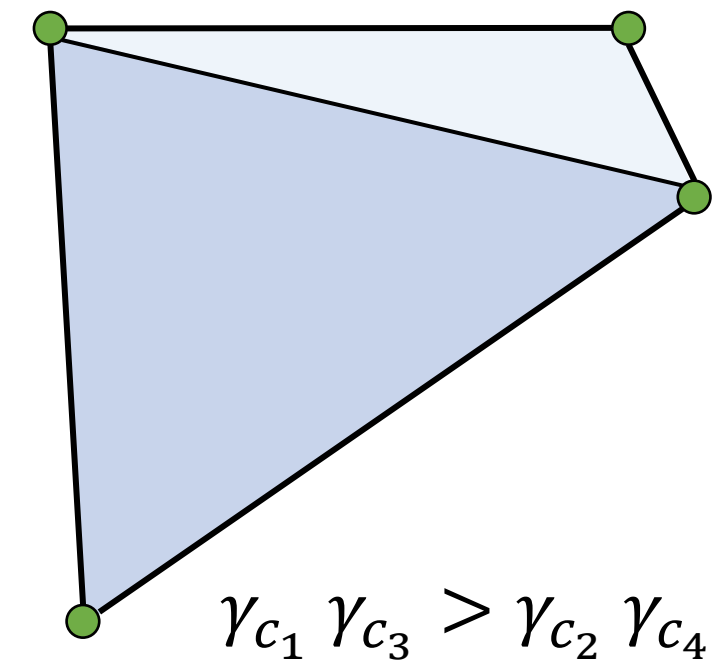
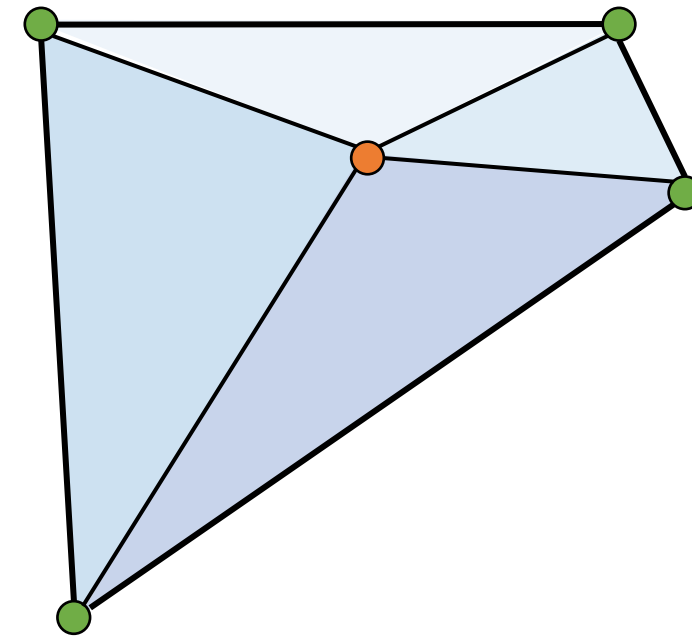
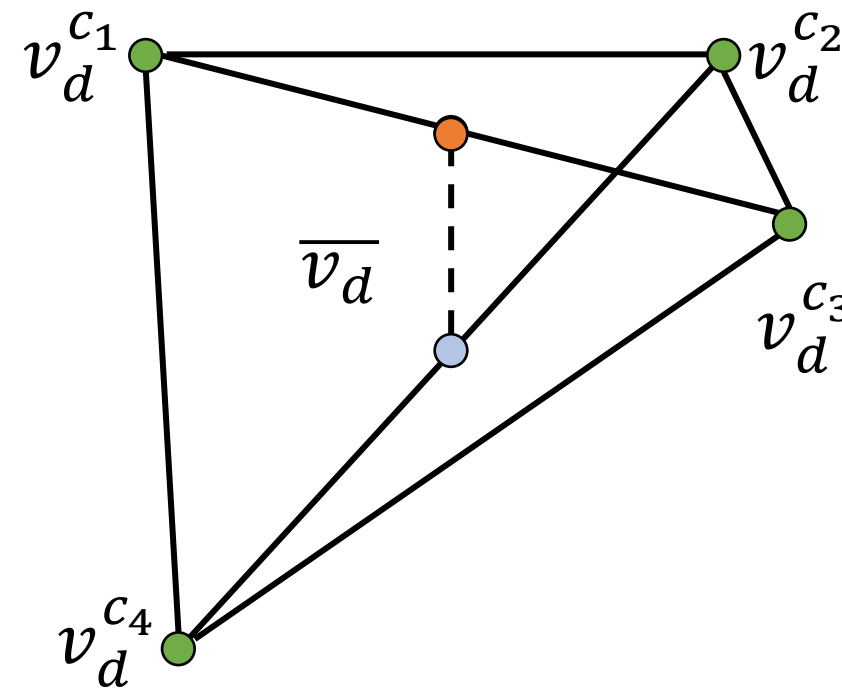
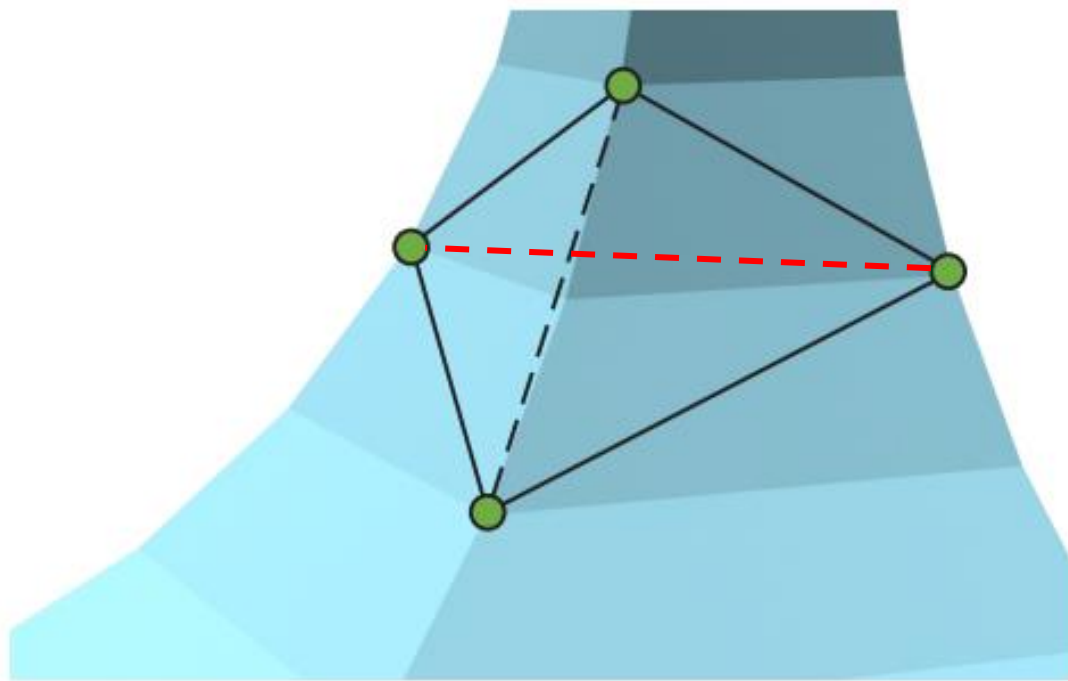
EXTRACTING FACES



SPLITTING WEIGHTS

Raw output from Dual Contouring are quadrilateral faces.

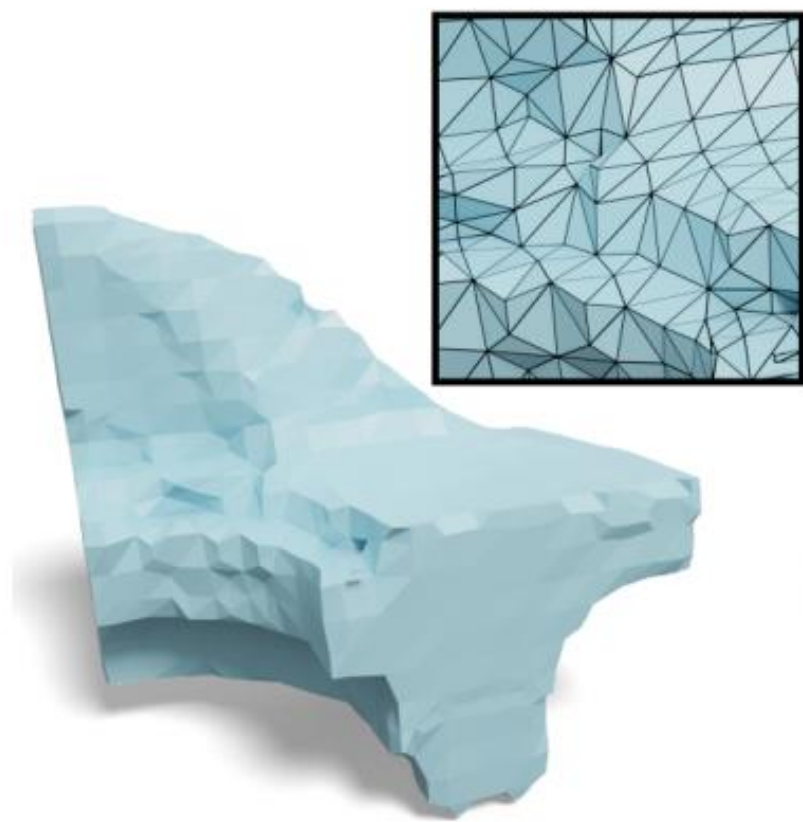
- Quad-split weights γ controlling how quads get split to tris.



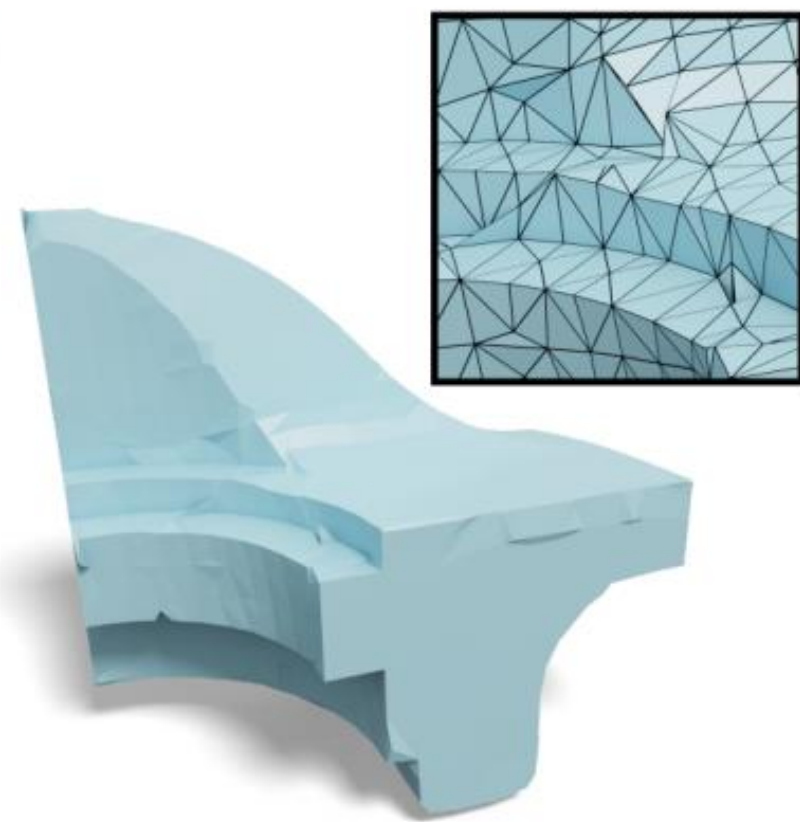
During **optimization**, γ interpolates the surface between two possible splits.

At **inference**, we split along the diagonal with dominant γ

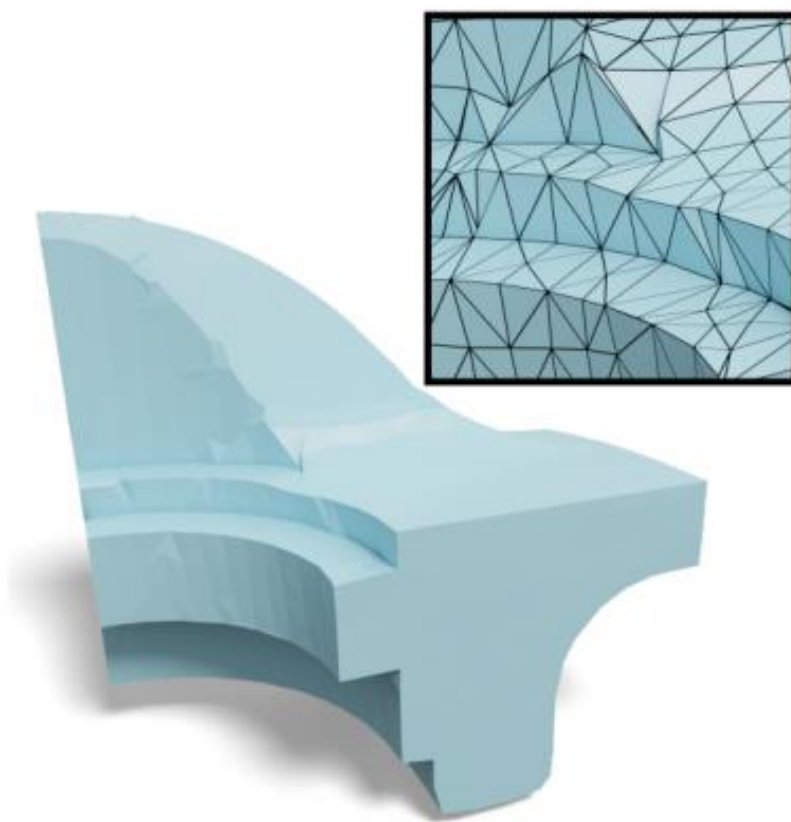
ABLATING PARAMETERS



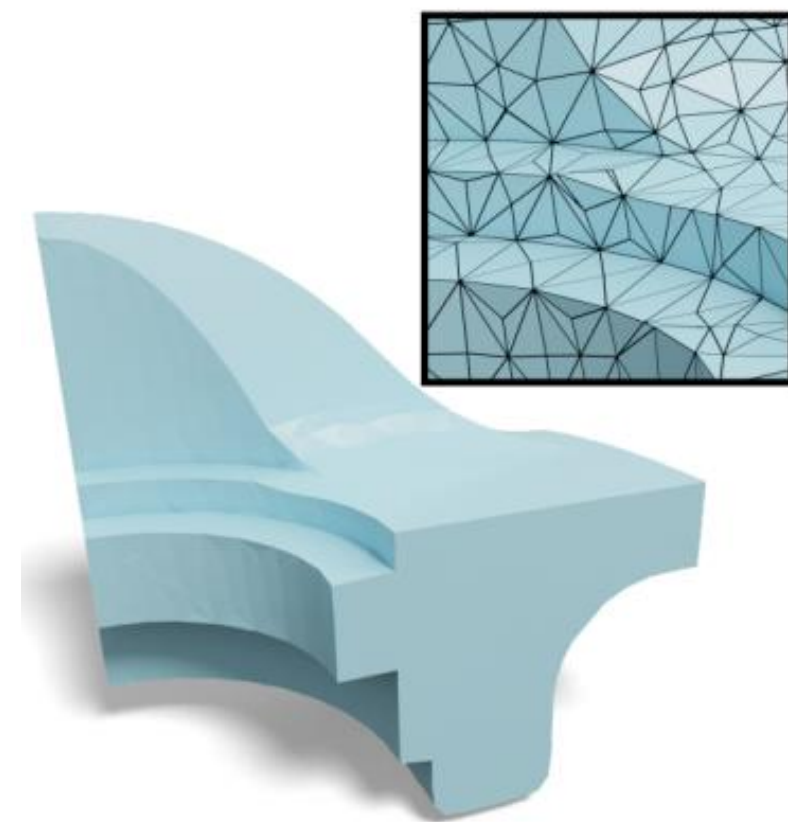
Baseline



+ interp. weights



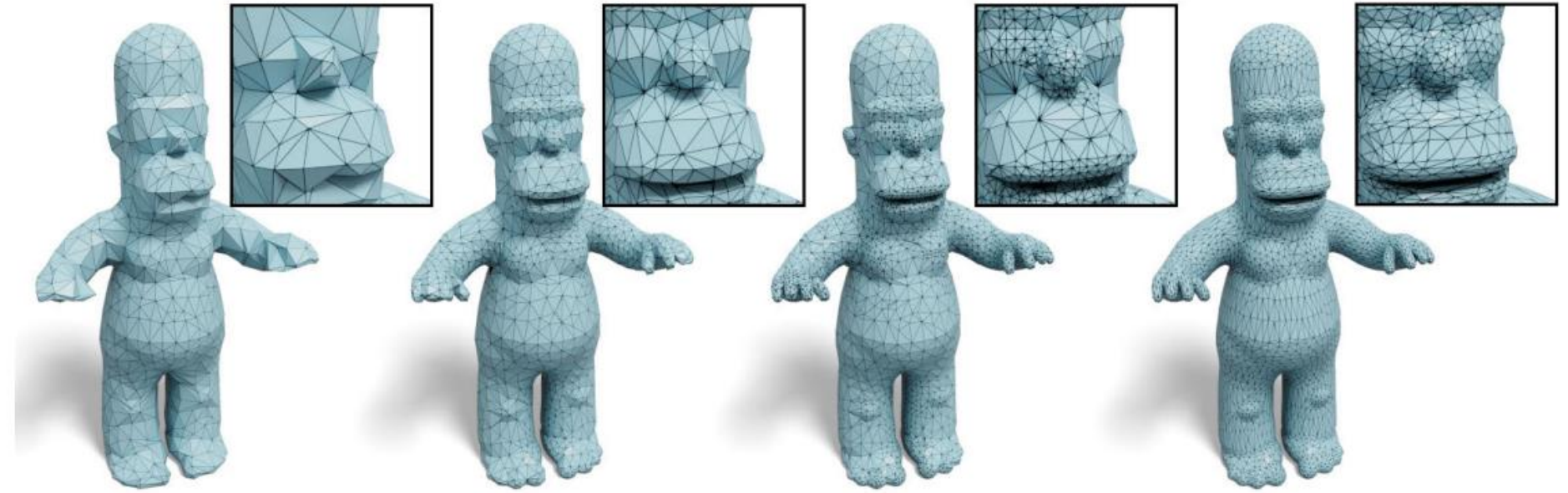
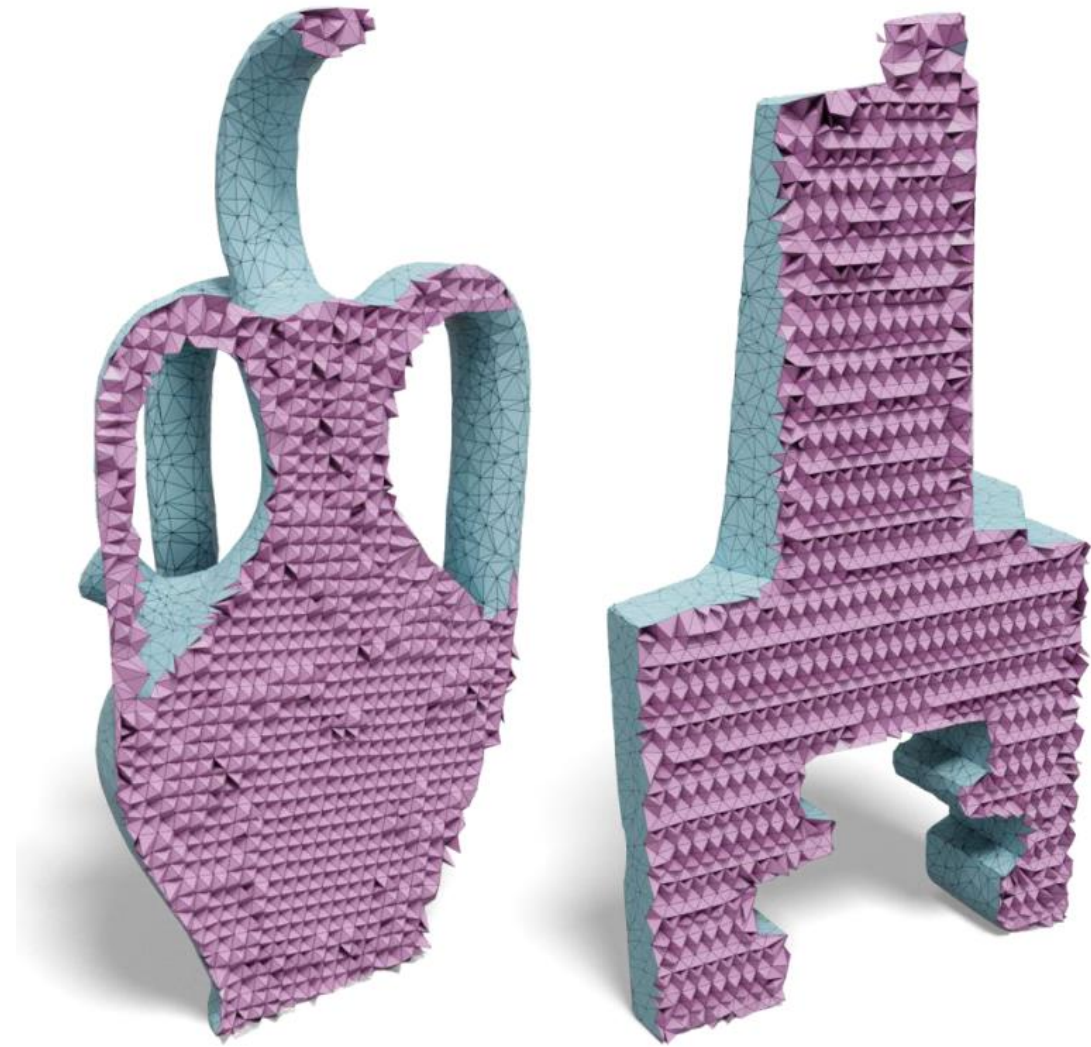
+ grid deform



+ split weights

EXTENSIONS

- Tetrahedral mesh extraction.
- Hierarchically adaptive meshing

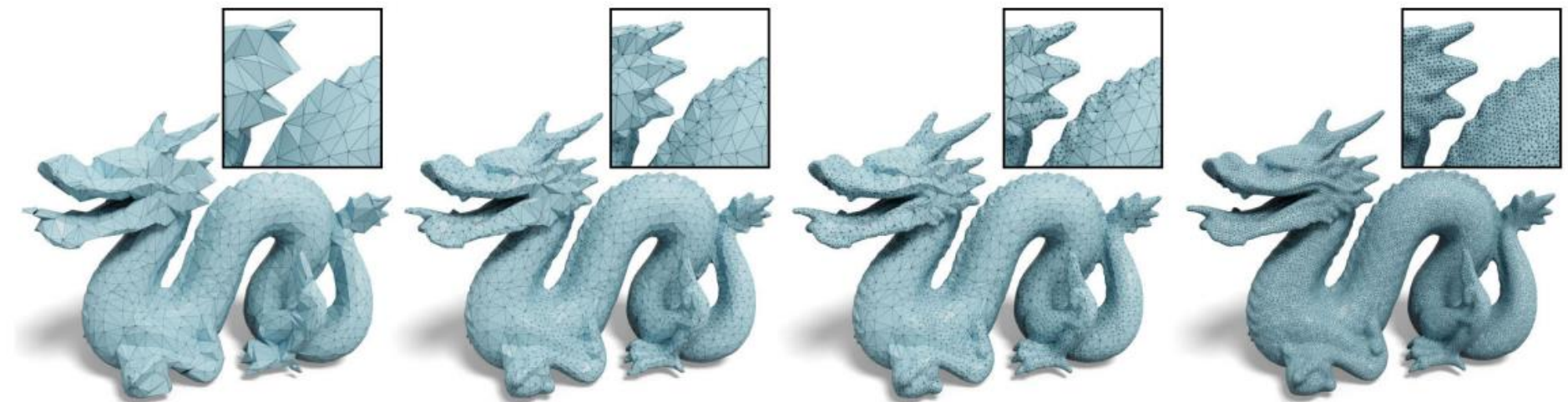


Uniform 32³
2.1k tris, CD:4.3

Adaptive 64³
4.5k tris, CD:2.5

Adaptive 128³
7.6k tris, CD: 2.4

GT
10k tris



Uniform 32³
2.1k tris, CD:5.7

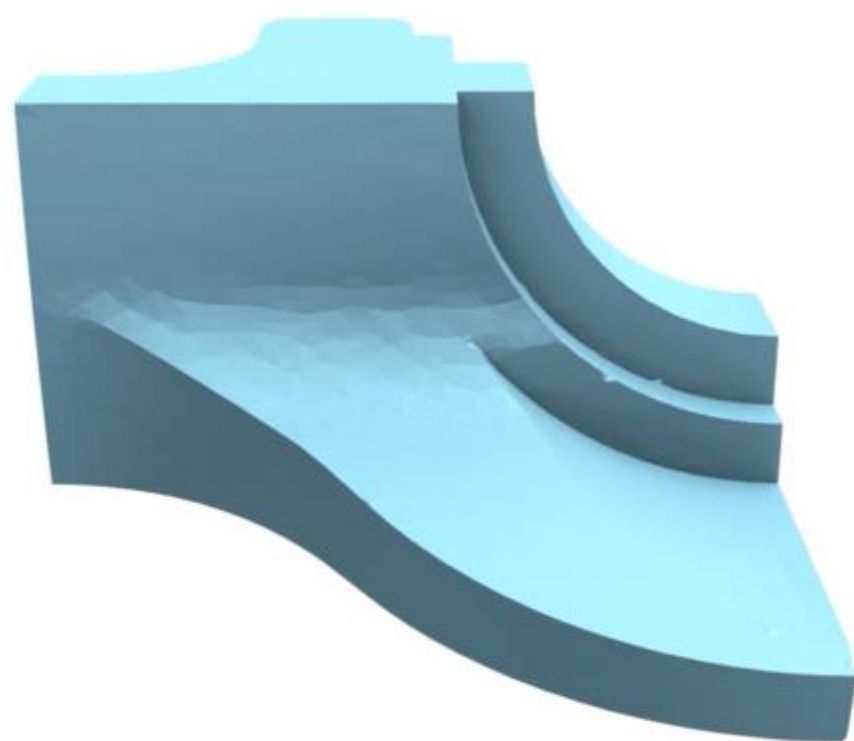
Adaptive 64³
5.7k tris, CD:4.7

Adaptive 128³
22k tris, CD: 4.4

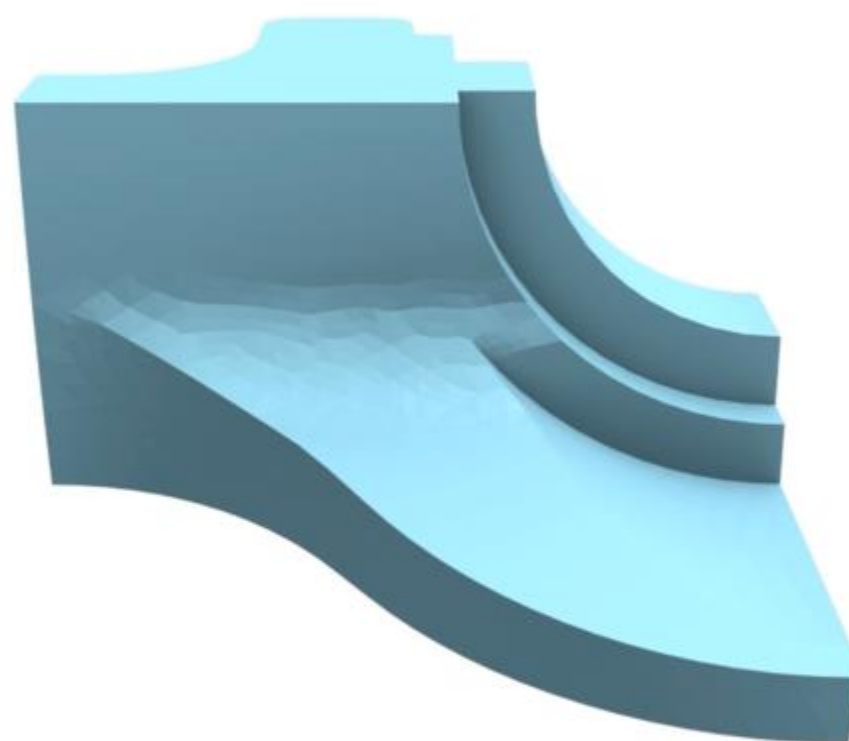
GT
104k tris

VALIDATIONS

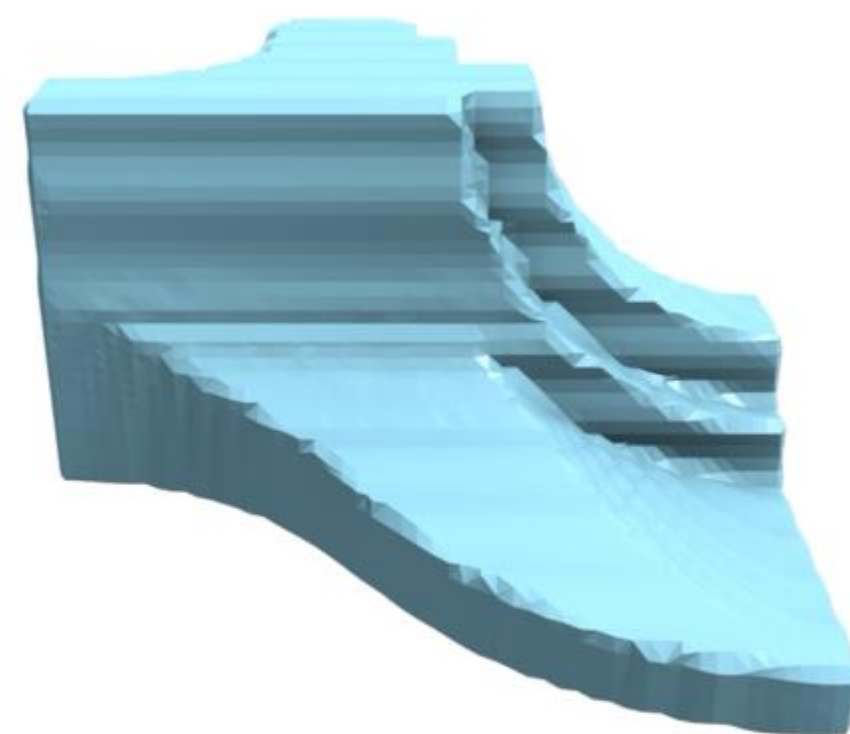
VISUAL COMPARISON



FlexiCubes



Reference



Marching Cubes (MC_SDF)

Baselines

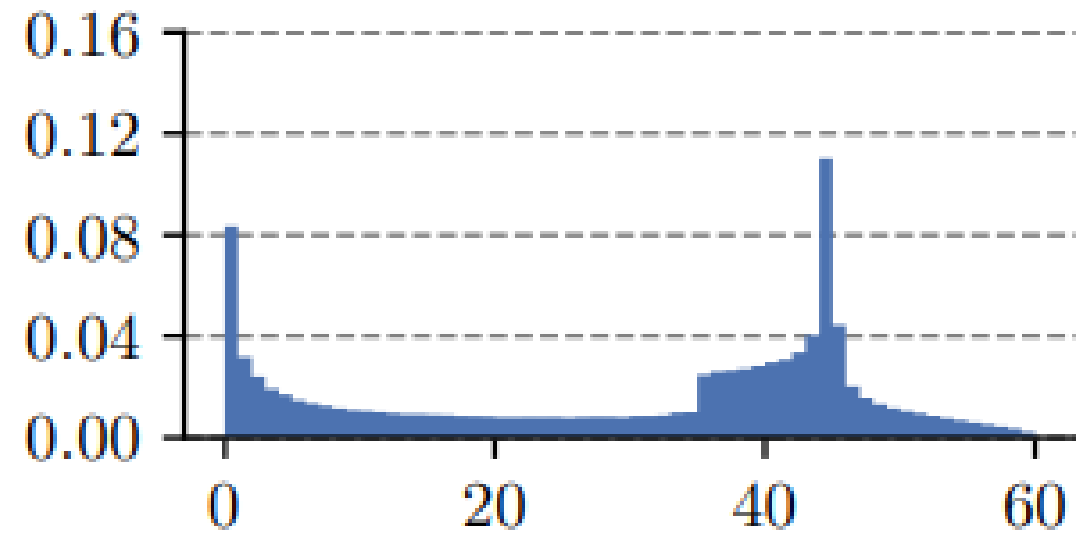
QUANTITATIVE COMPARISONS OF RECONSTRUCTION ERROR

Evaluated on dataset collected by Myles et al. [2014] which contains 79 highly-detailed, diverse 3D shapes.

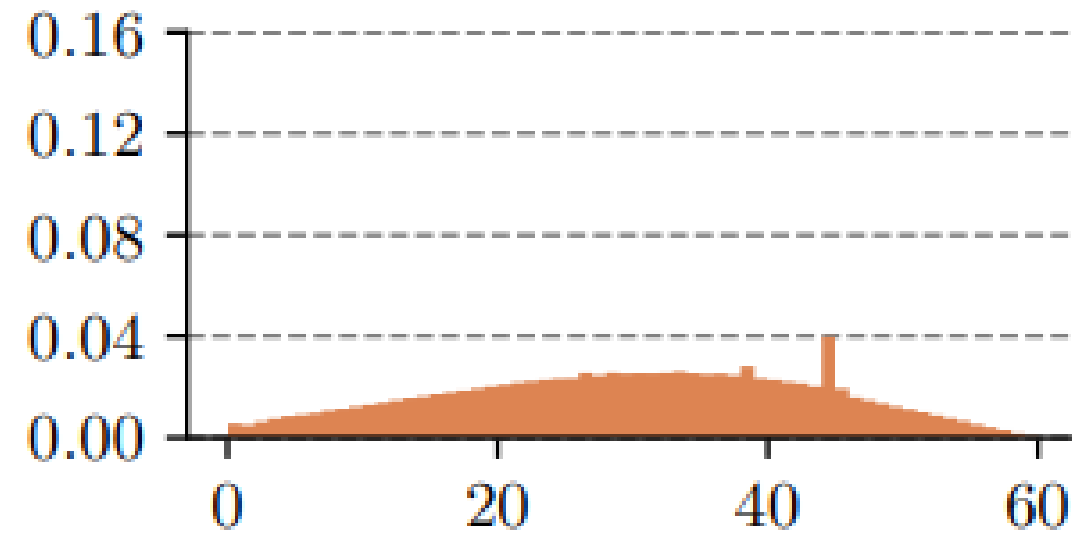
		64^3	CD(10^{-5}) ↓	F1 ↑	ECD (10^{-2}) ↓	EF1 ↑
Extracting mesh from ground truth SDF	MC_{SDF}		6.84	0.55	2.55	0.14
	$DC_{hermite}$		5.90	0.61	3.80	0.23
	NDC_{SDF}		6.16	0.57	1.22	0.26
Reconstruct mesh via optimization	MC		6.33	0.66	1.25	0.25
	DMTet(64)		7.50	0.66	3.77	0.28
	DMTet(80)		5.17	0.66	3.59	0.29
	FLEXICUBES		4.87	0.70	0.71	0.43
		128^3	CD(10^{-5}) ↓	F1 ↑	ECD (10^{-2}) ↓	EF1 ↑
	MC_{SDF}		4.72	0.68	1.13	0.33
	$DC_{hermite}$		4.59	0.69	3.82	0.40
	NDC_{SDF}		5.04	0.65	0.79	0.43
	MC		4.51	0.72	1.32	0.44
	DMTet(128)		4.98	0.74	1.50	0.39
	FLEXICUBES		4.31	0.71	0.42	0.51

BETTER TRIANGLE QUALITY

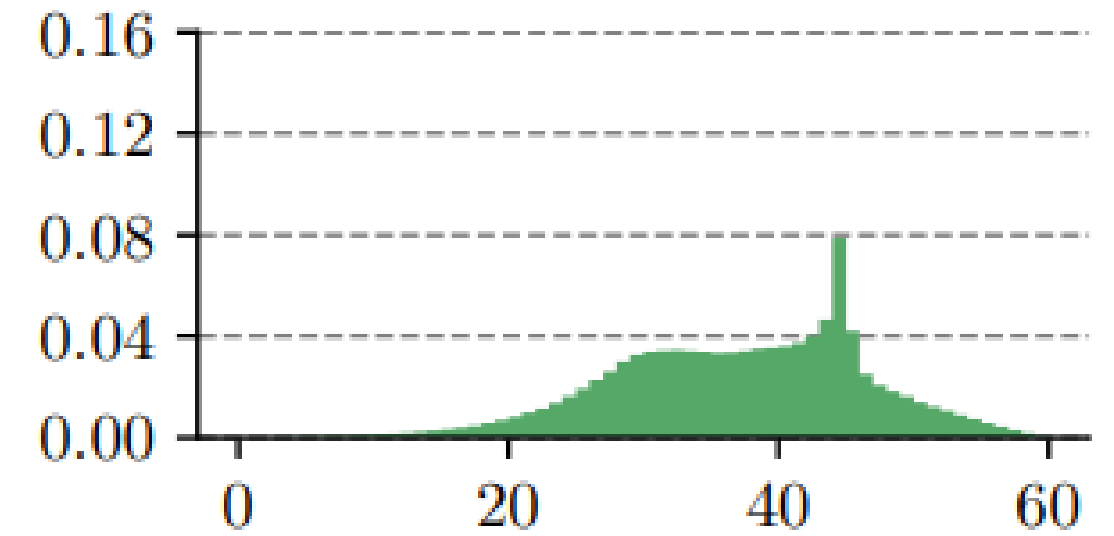
Min angle of extracted triangles.



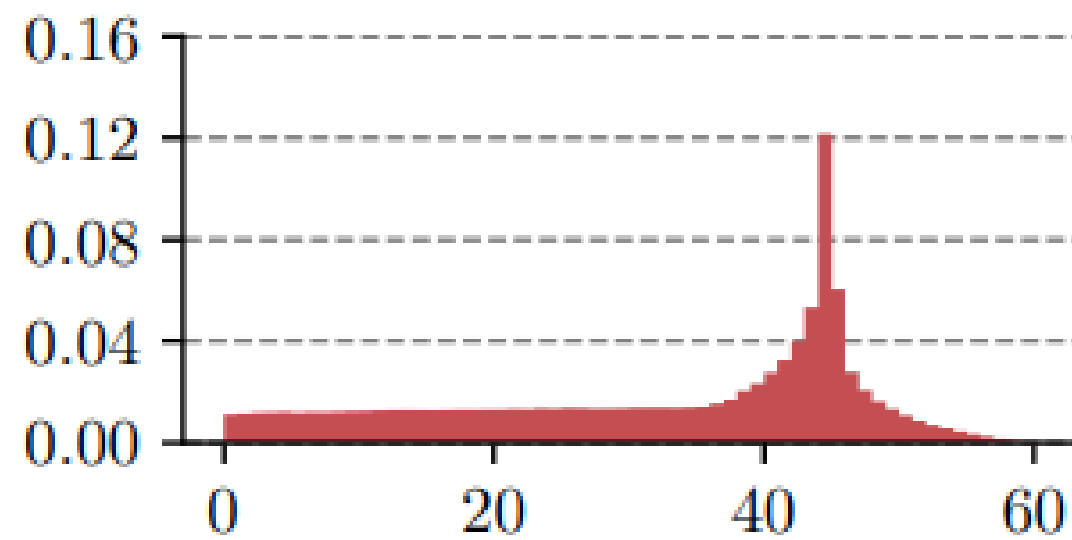
MC_{SDF}



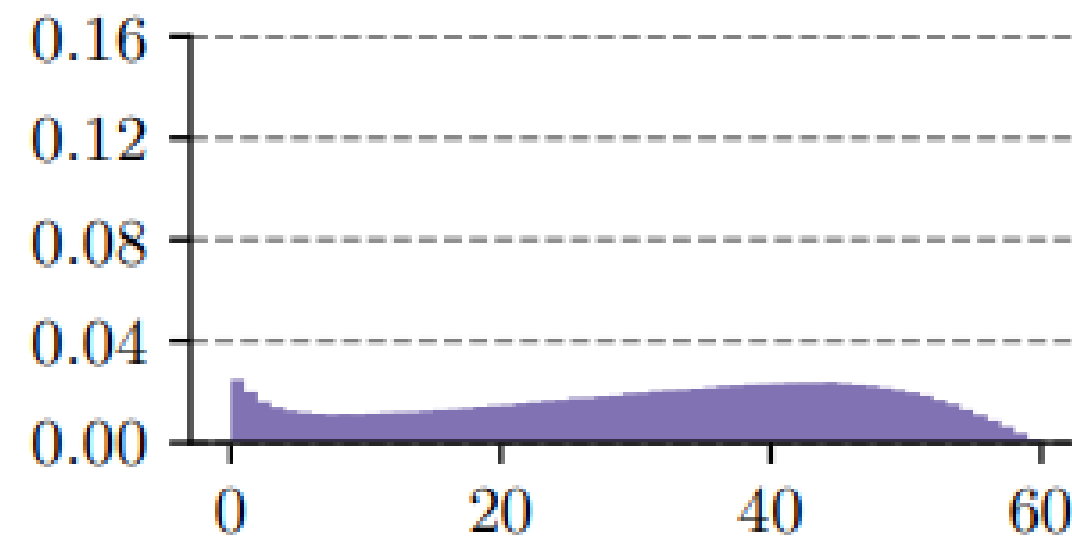
DC



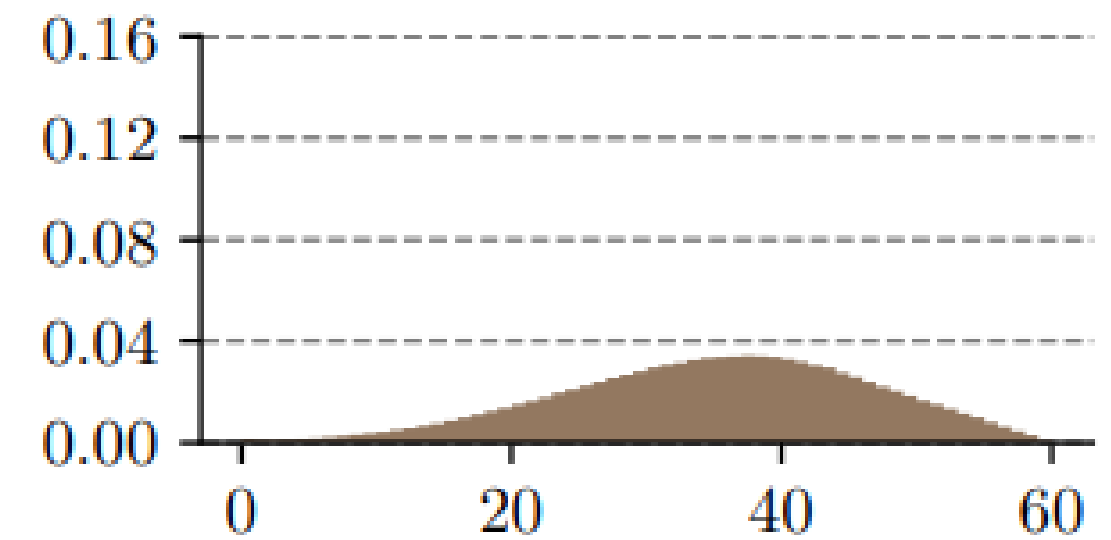
NDC



MC



$DMTet$

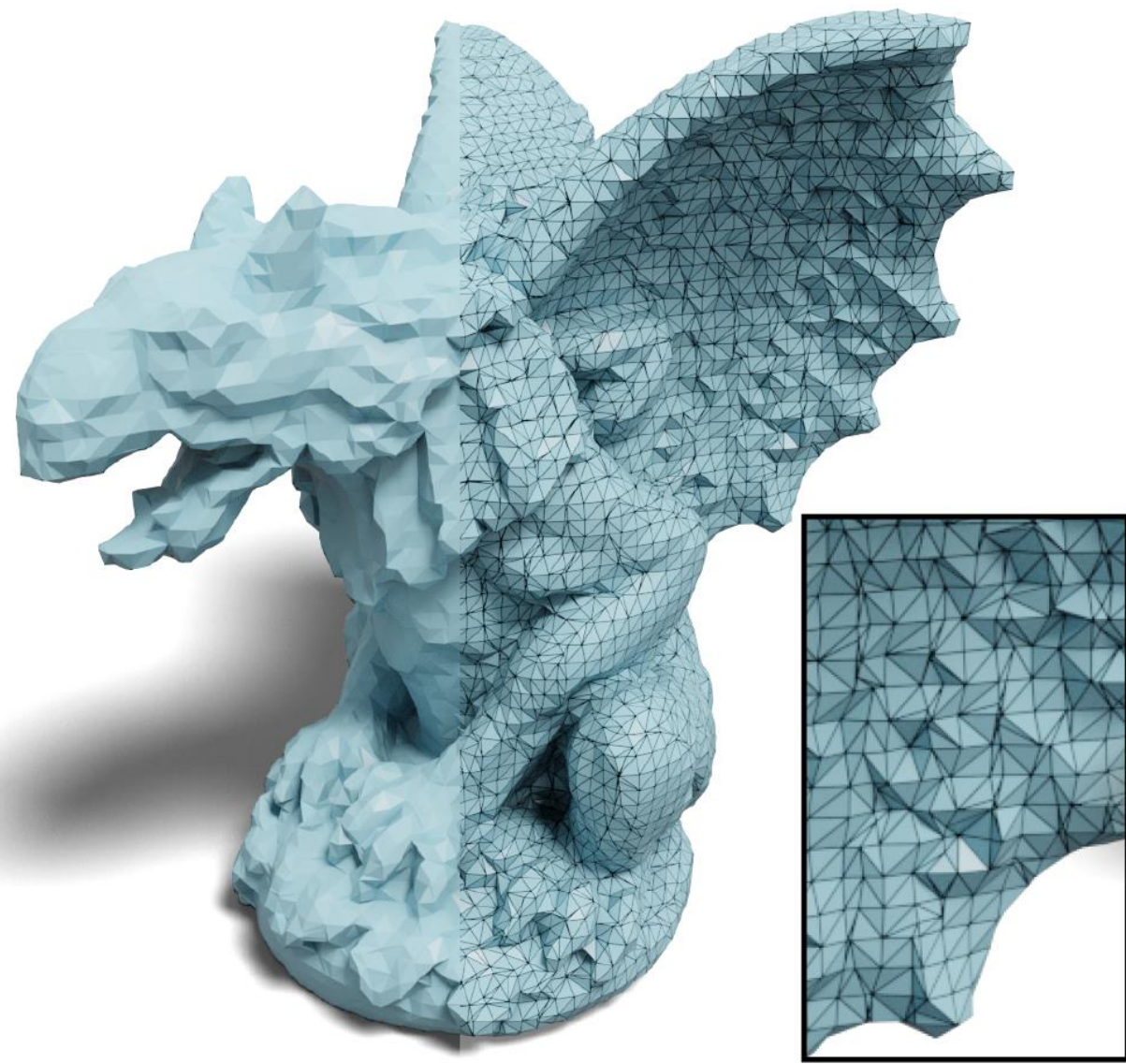


$FlexiCubes$

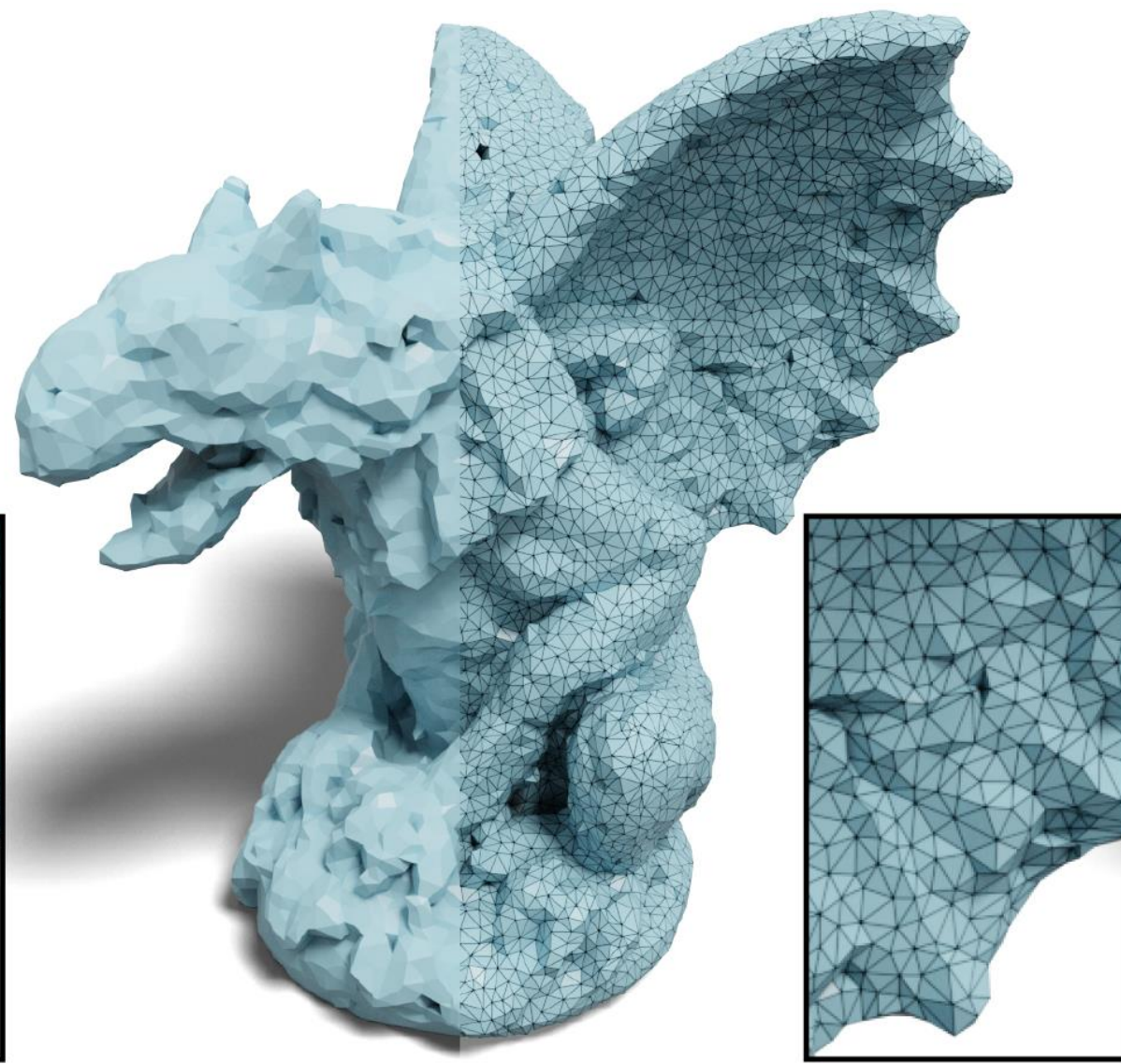
MESH OPTIMIZATION WITH REGULARIZATIONS

We can further improve triangle quality by adding additional regularizers.

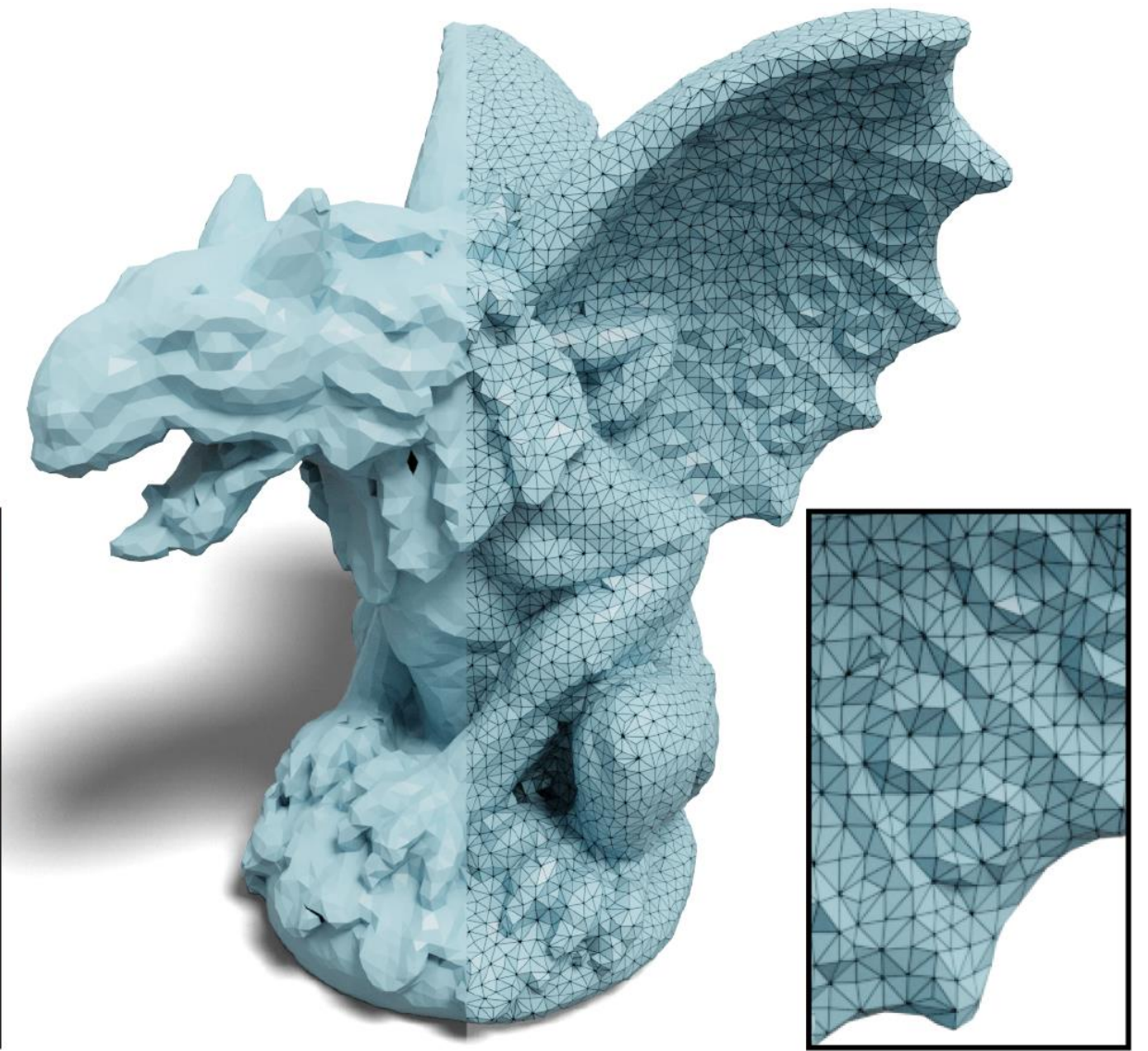
- Equilateral Edge Length



MC



DMTet

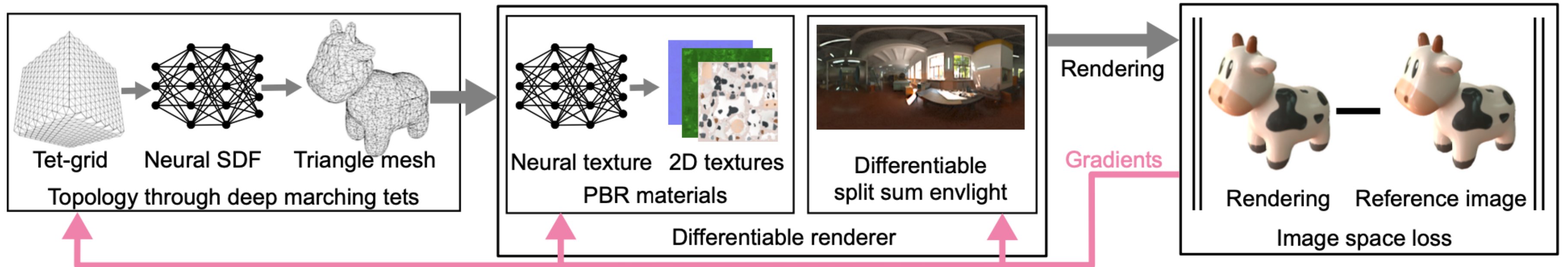


FlexiCubes

APPLICATIONS

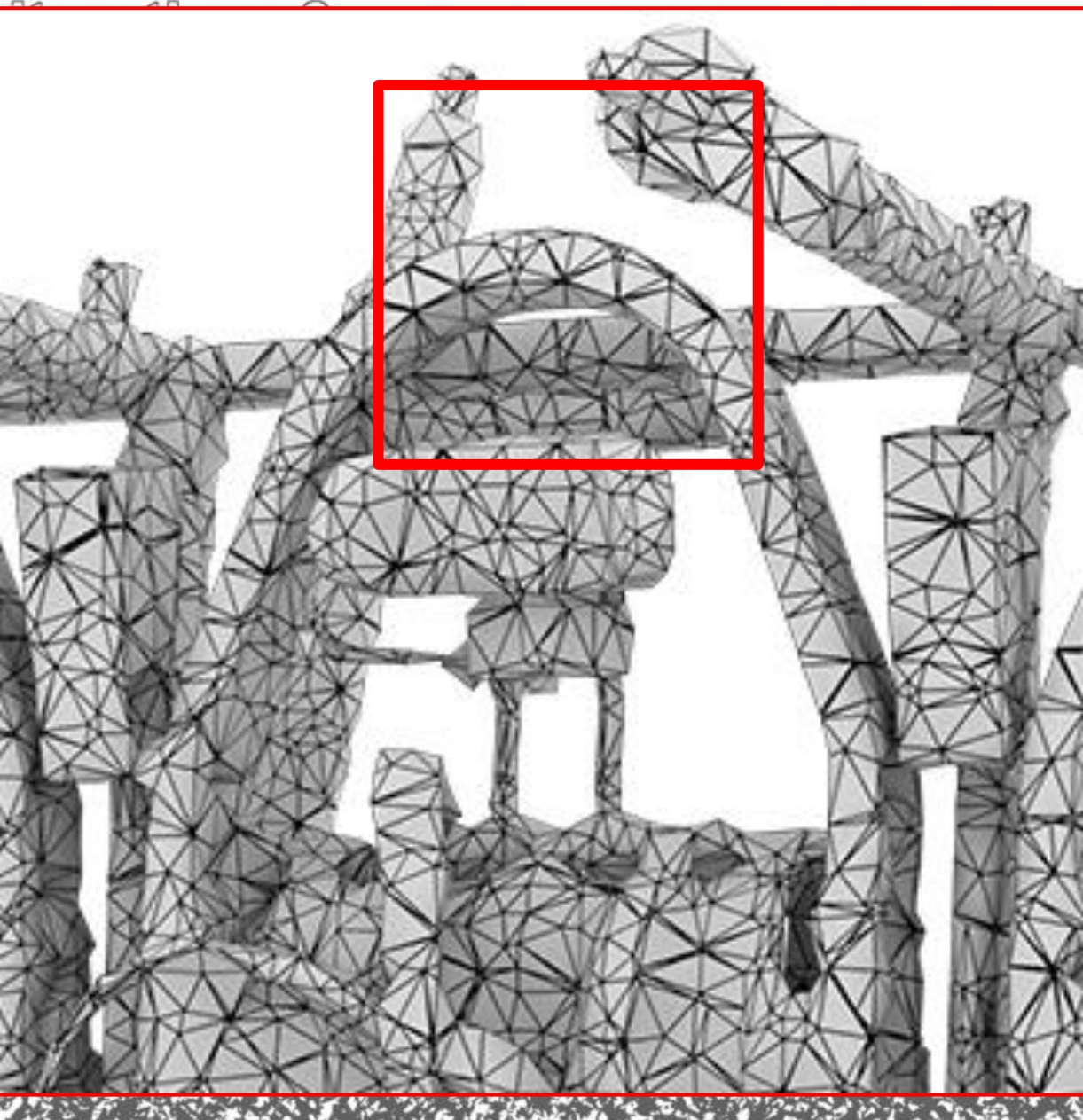
PHOTOGRAMMETRY THROUGH DIFFERENTIABLE RENDERING

Nvdiffrrec jointly optimizes shape, materials, and lighting from images.

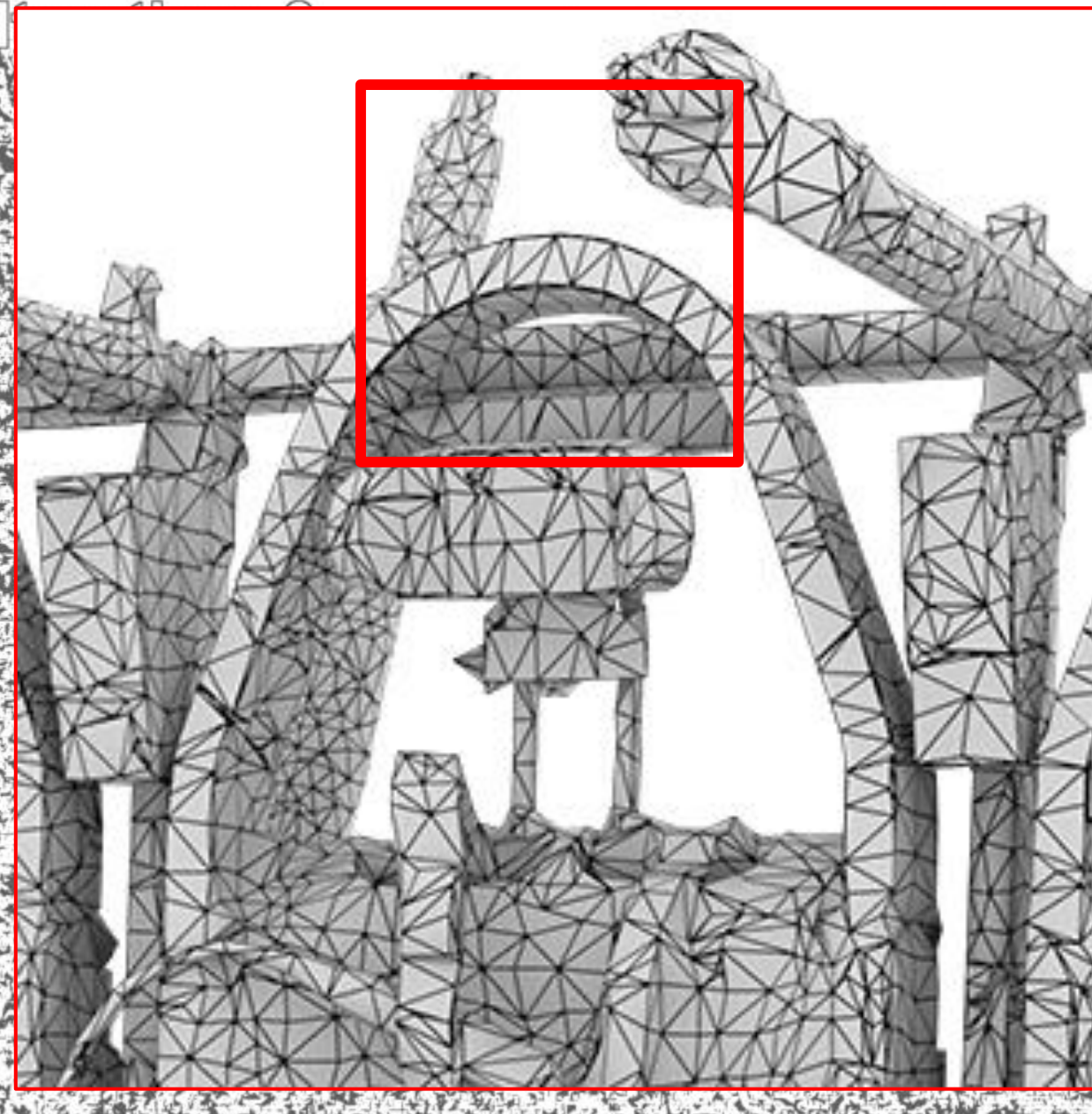


PHOTOGRAMMETRY THROUGH DIFFERENTIABLE RENDERING

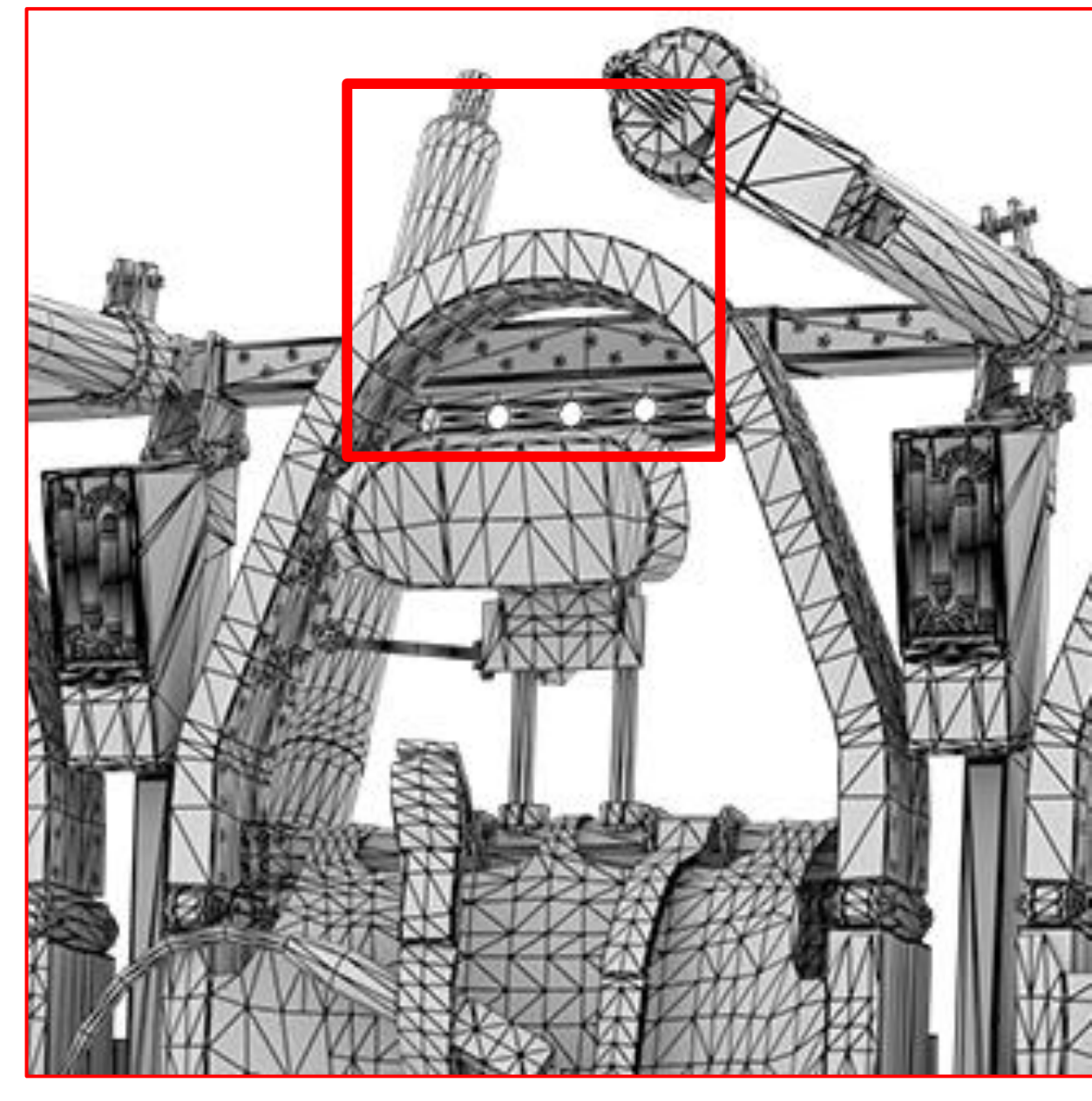
FlexiCubes improves geometric fidelity and mesh quality.



Nvdiffrac w/ DMTet



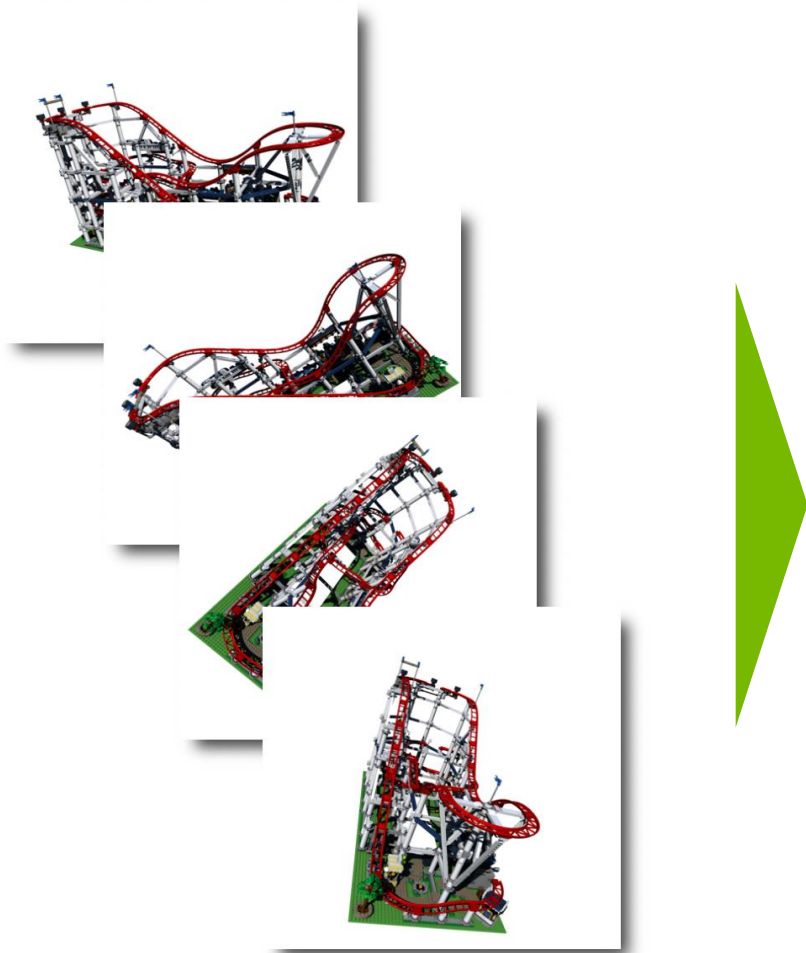
Nvdiffrac w/ **FlexiCubes**



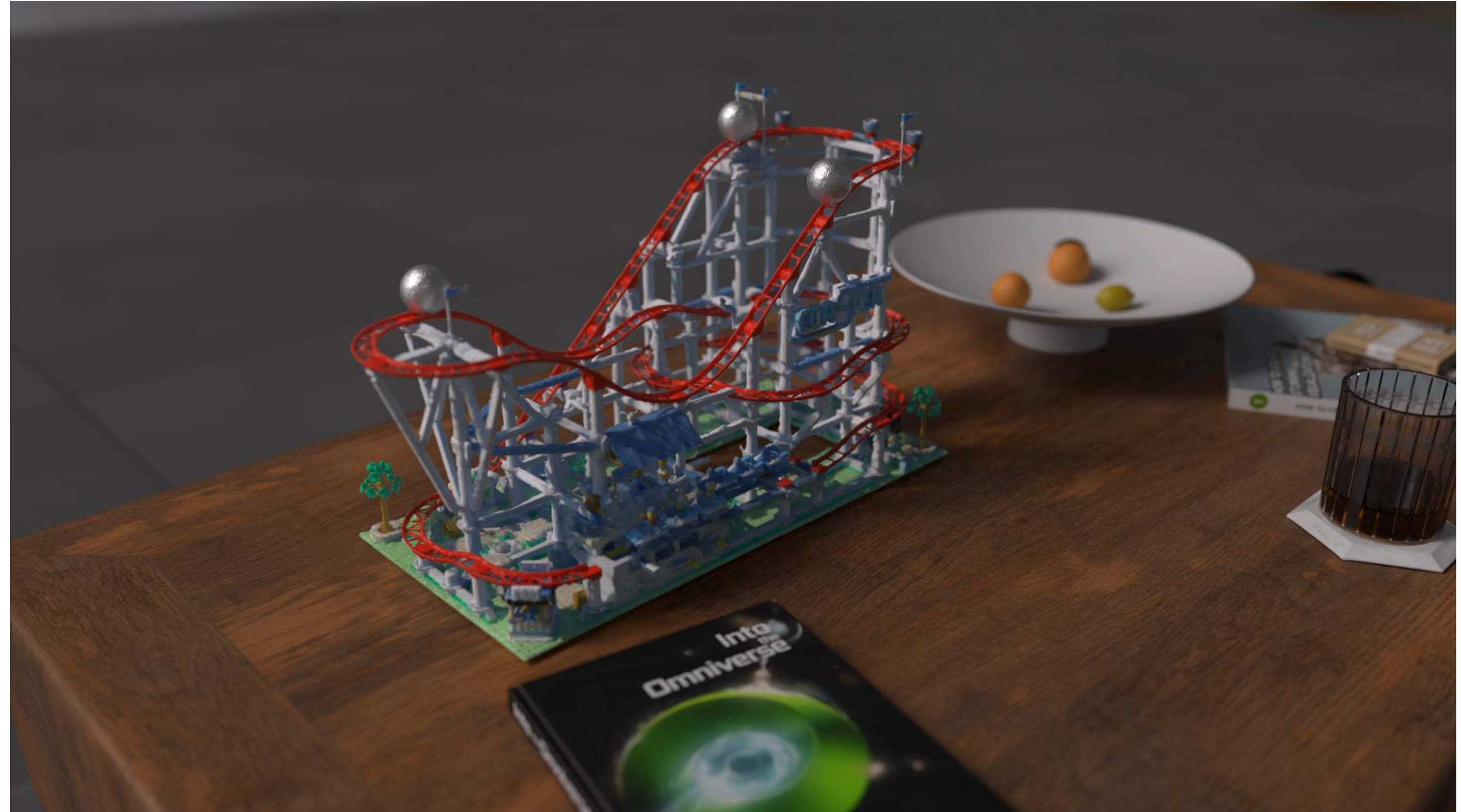
Reference

PHOTOGRAMMETRY THROUGH DIFFERENTIABLE RENDERING

The outputs are compatible with standard graphics workflow.



Multiview inputs



Simulating reconstructed asset with physics in Omniverse

MESH SIMPLIFICATION OF ANIMATED OBJECTS

End-to-end optimization w/ **FlexiCubes** avoids mesh stretching.



End-to-end optimization

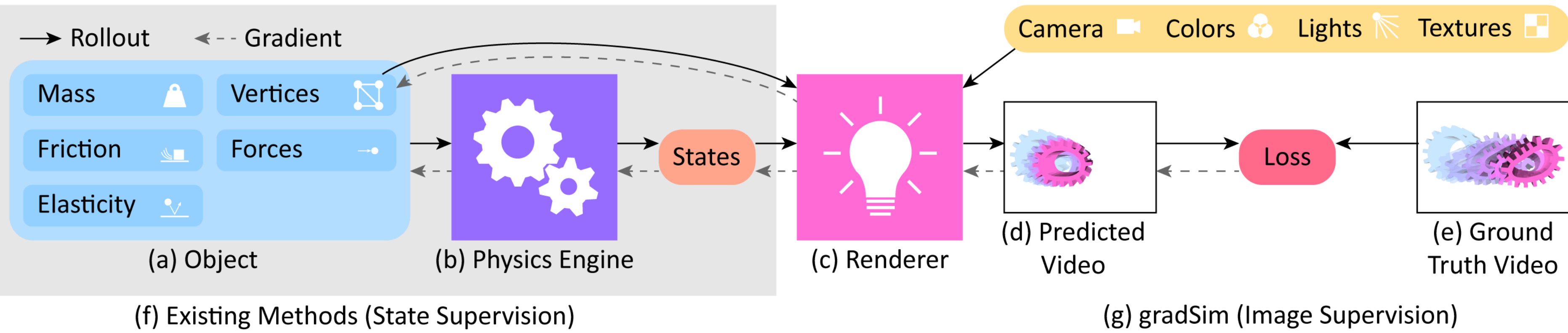


Reference



T-pose optimization

DIFFERENTIABLE PHYSICS SIMULATION WITH TET MESH



DIFFERENTIABLE PHYSICS SIMULATION WITH TET MESH



Initialization

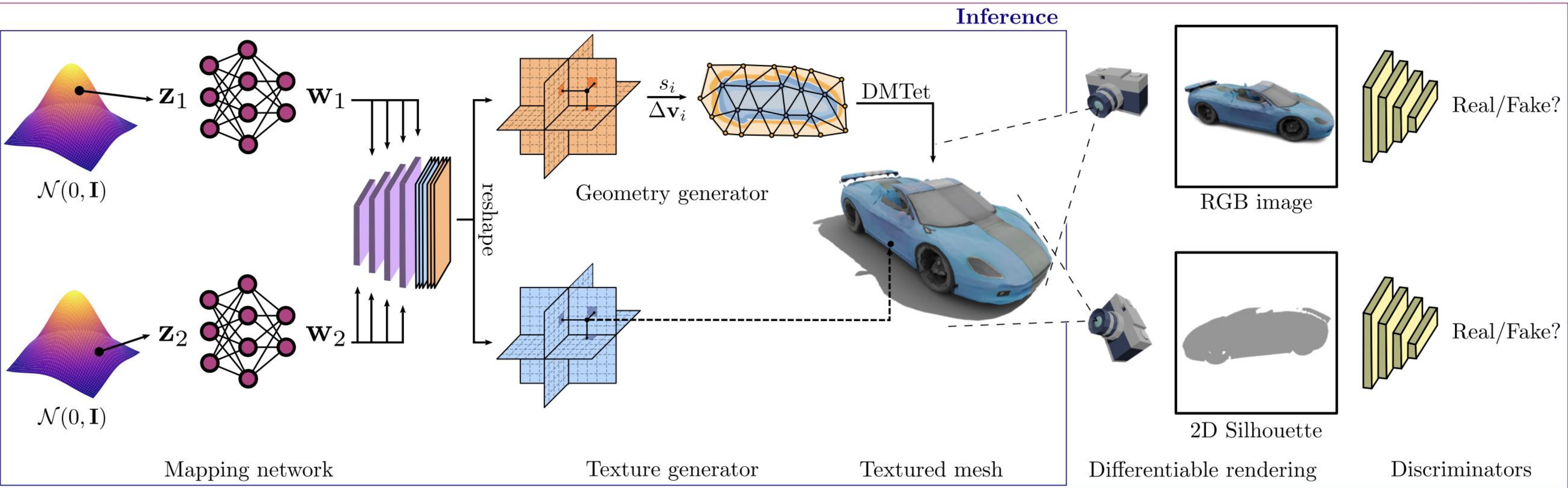
Optimized Results w/ **FlexiCubes**

Reference

3D GENERATIVE MODELING FOR MESHES W/ GET3D

Training

Inference



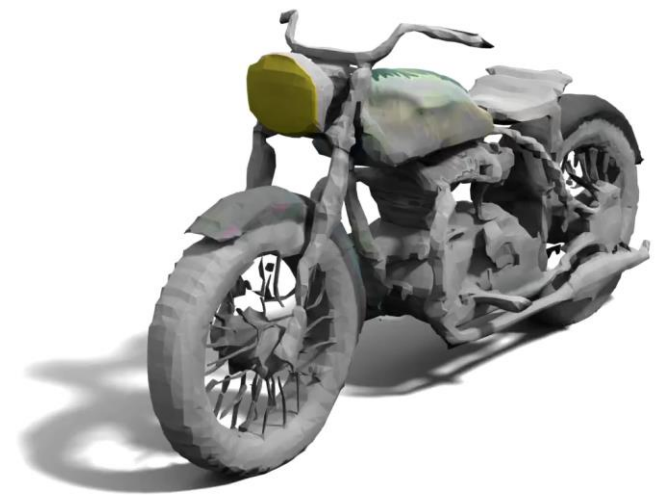
3D GENERATIVE MODELING FOR MESHES W/ GET3D

GET3D w/ **FlexiCubes** generates meshes with better details and tessellation.

DMTet



FlexiCubes



Motorbike

Chair

Car

3D GENERATIVE MODELING FOR MESHES W/ GET3D

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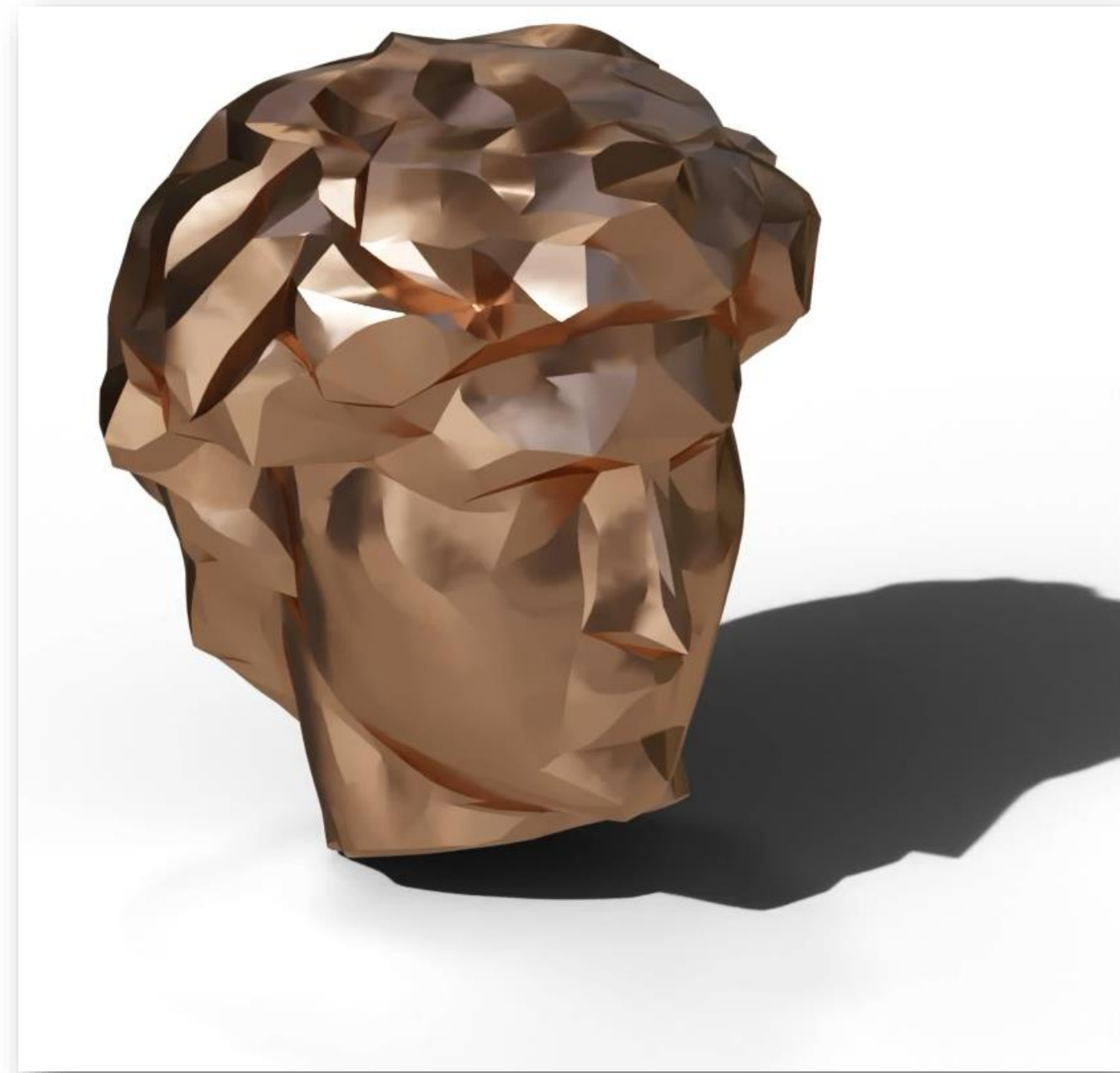
Car

ADDING MESH REGULARIZATIONS

FlexiCubes supports optimizing regularizations defined on meshes.



Marching Cubes



FlexiCubes

PERFORMANCE

Performance of Isosurfacing operations

128^3	Forward Time (ms)	Backward Time (ms)	Memory (MB)
MC	5.08	0.58	72.85
DMTet	6.94	1.39	168.27
<i>DMC_{centroid}</i> [Nielson 2004]	7.34	1.74	150.75
FLEXICUBES	14.06	9.53	816.17

Performance of various application (1 iteration)

Applications (96^3)	NVDIFFRECMC		GET3D	
Isosurface	DMTet	FLEXICUBES	DMTet	FLEXICUBES
Time per iter. (ms)	307	315	510	610
Memory(GiB)	13.1	15.3	11.6	11.1

LIMITATIONS AND FUTURE WORK

Limitations:

- Self-intersections
- Weaker guarantees of topological correctness in adaptive and tetrahedral meshing.

Future work:

- Integrate volumetric rendering with mesh-based representation.
- Extend to 4D spatiotemporal meshing.
- Integrate adaptive hierarchical meshing into generative modeling pipelines.

THANK YOU FOR LISTENING!

Takeaways:

- **FlexiCubes** is designed for gradient-based mesh optimization.
- Incorporate additional DoFs into mesh extraction.
- Drop-in replacement for better mesh quality and geometric fidelity!



Populate your 3D world with assets generated w/ **FlexiCubes!**

Visit our project page to explore additional results and learn more details!

